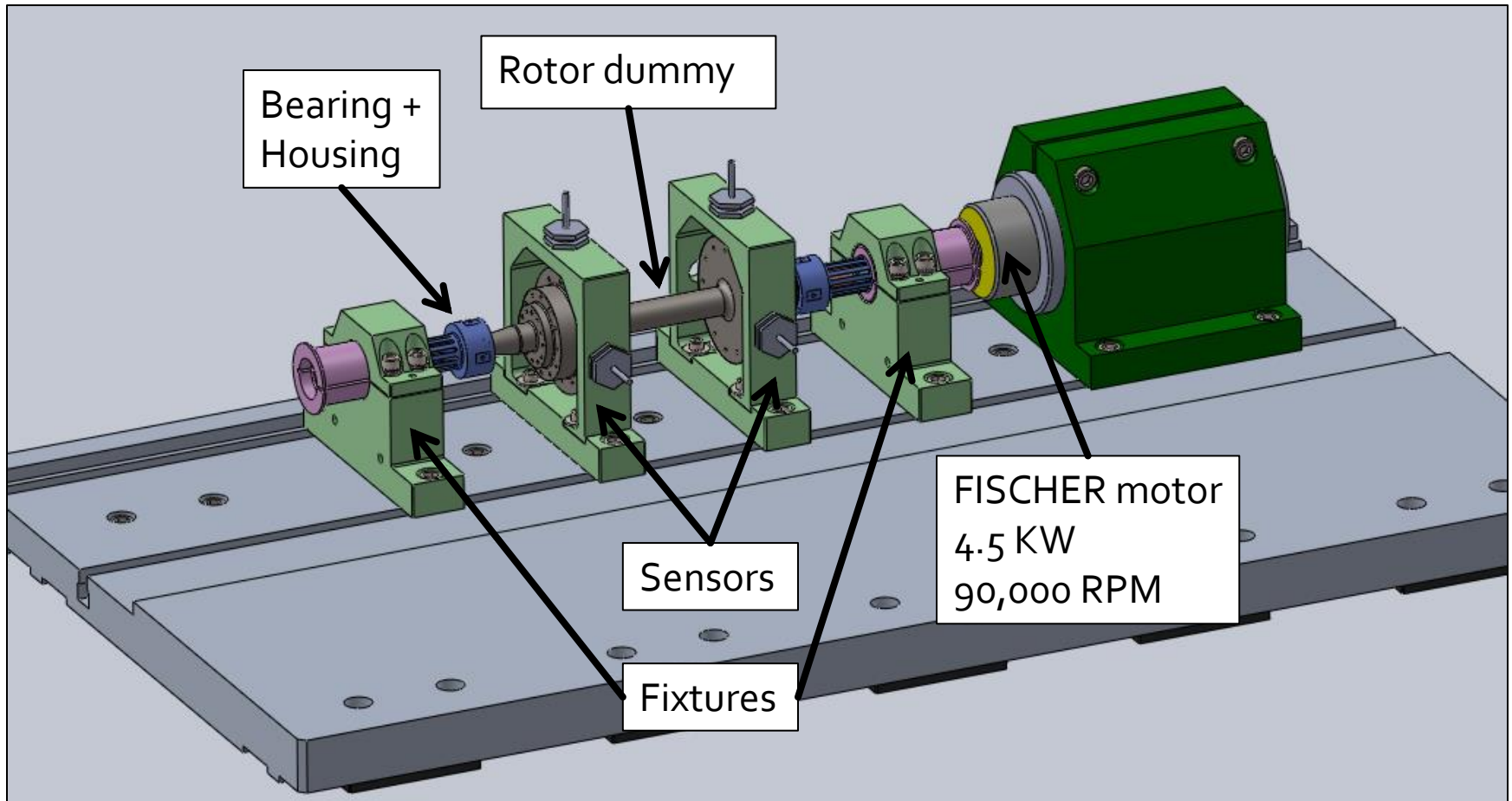


EXPERIMENTAL AND SIMULATED DYNAMICS OF A TURBO-JET ROTOR LABORATORY SIMULATOR

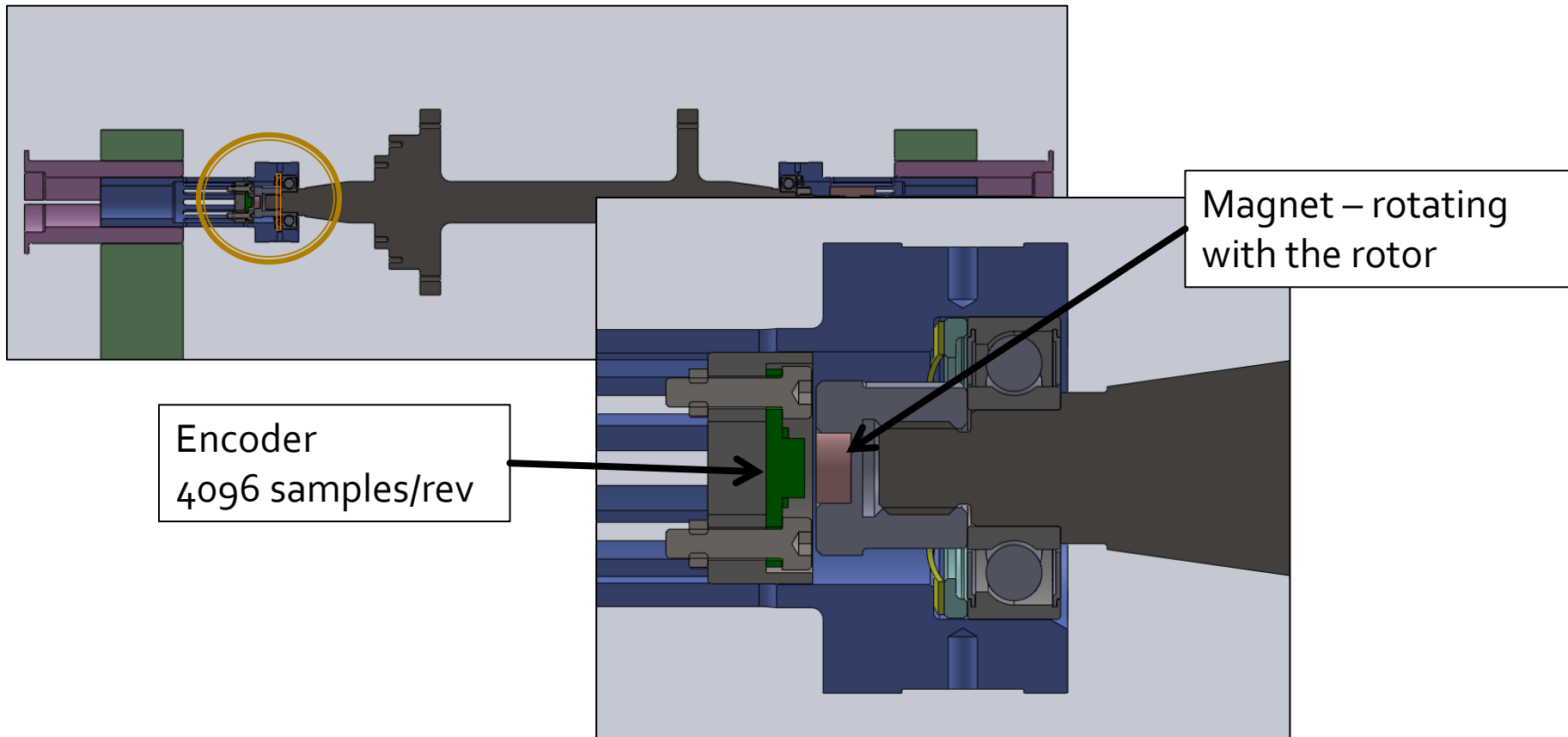
Alex Ferdinskoif and Prof. Izhak Bucher

Dynamics Laboratory
Mechanical Engineering
Technion - Israel Institute of Technology

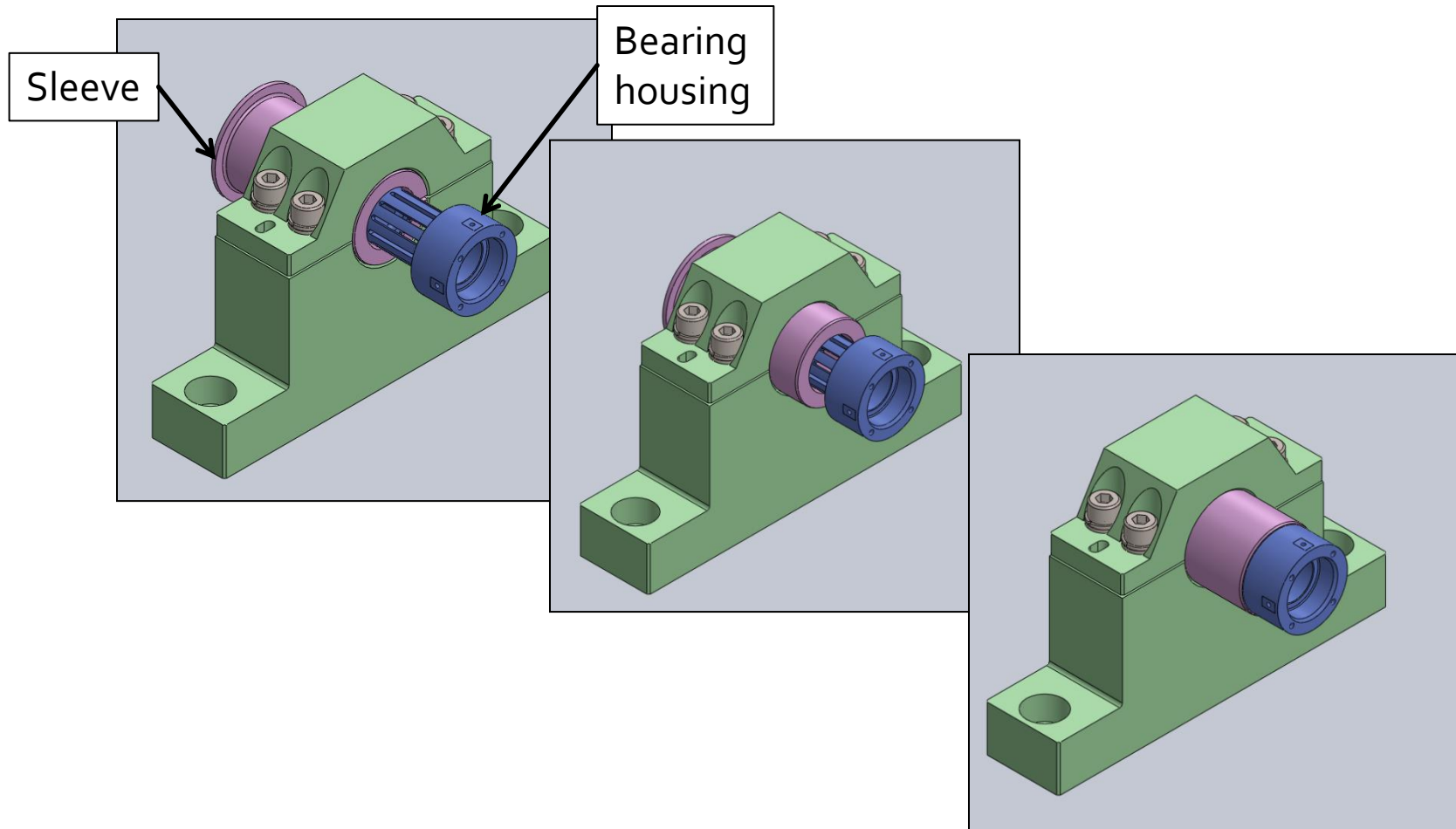
LABORATORY SIMULATOR



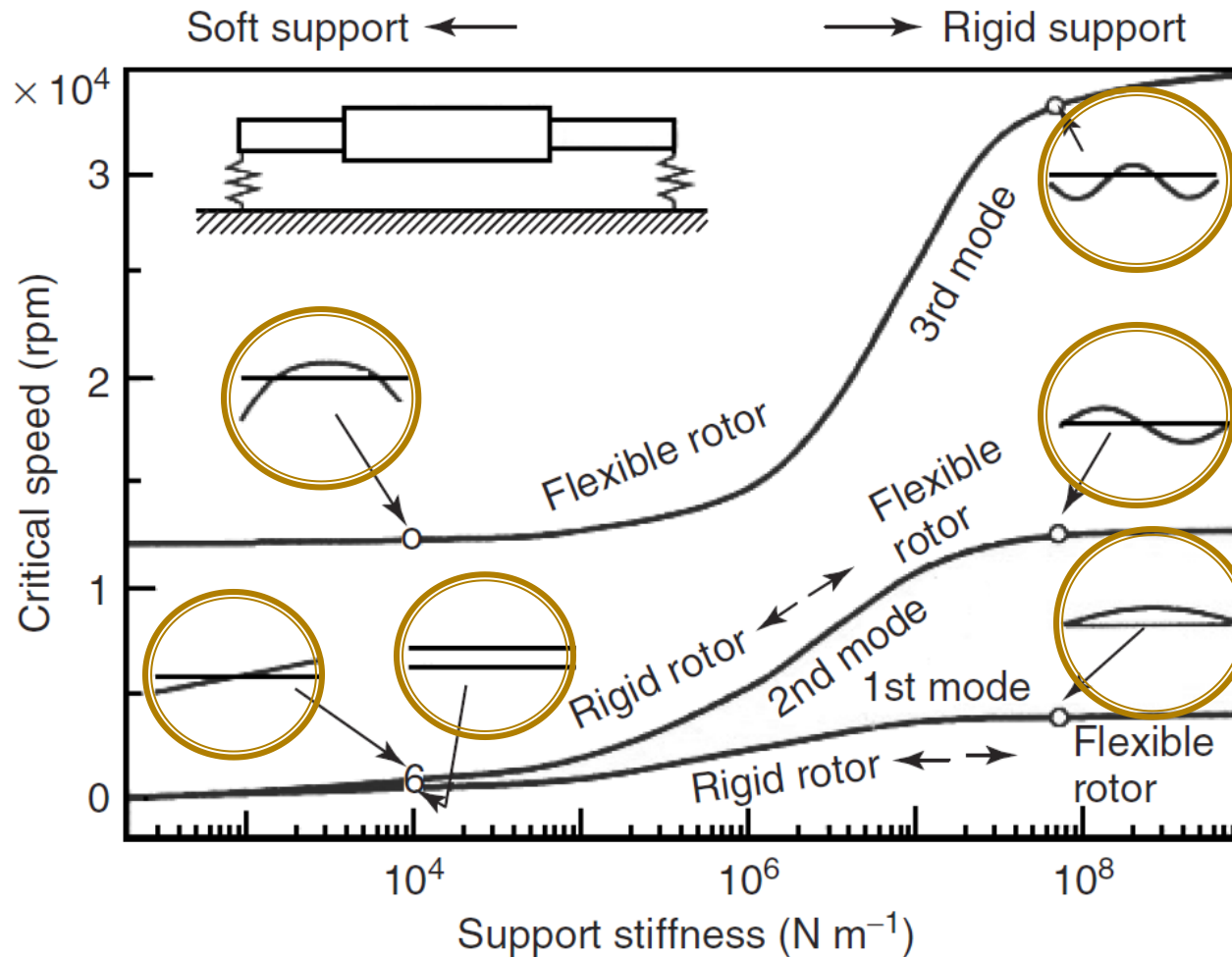
- Magnetic encoder



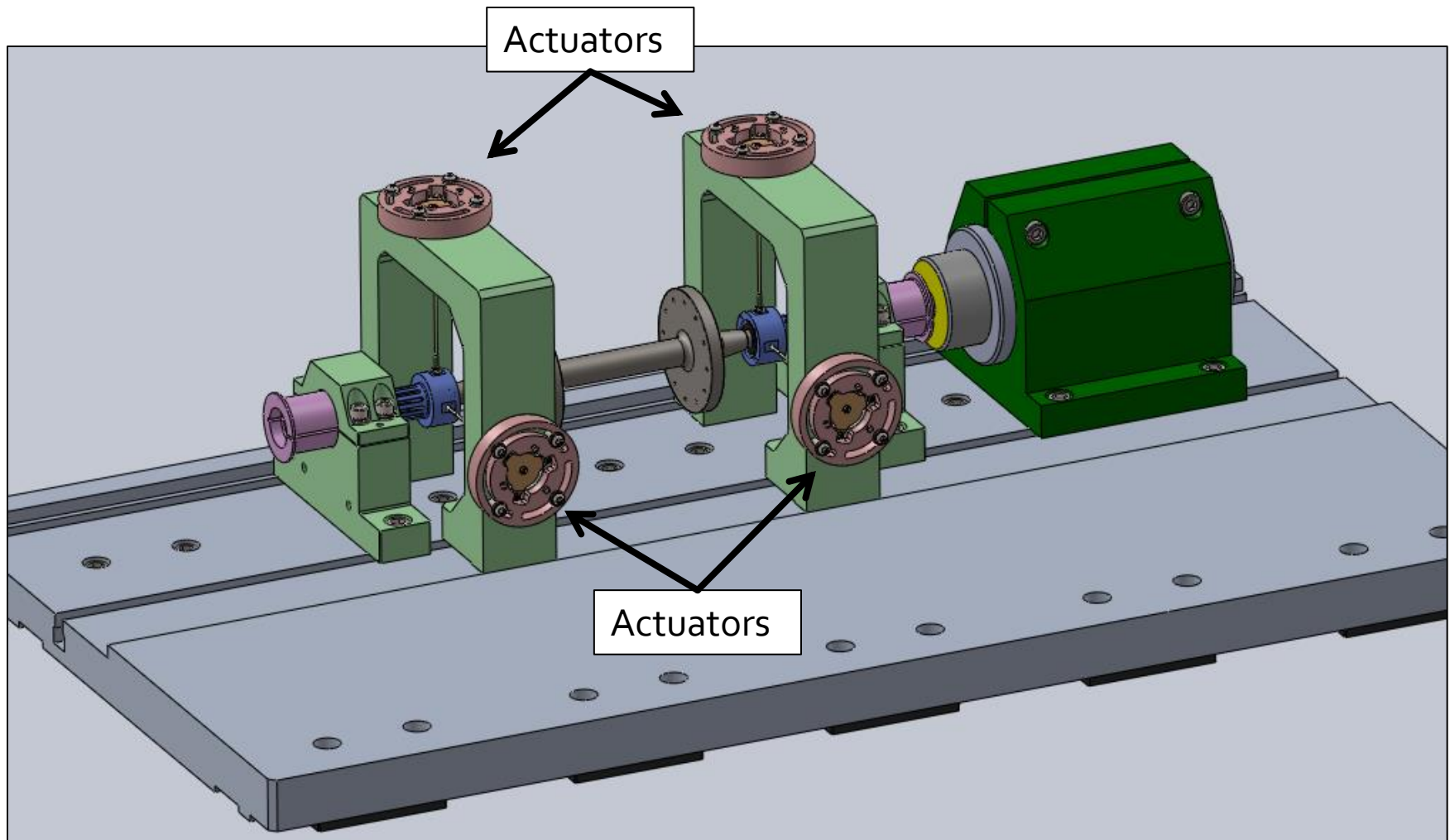
- Varying support's stiffness using adjustable spring element



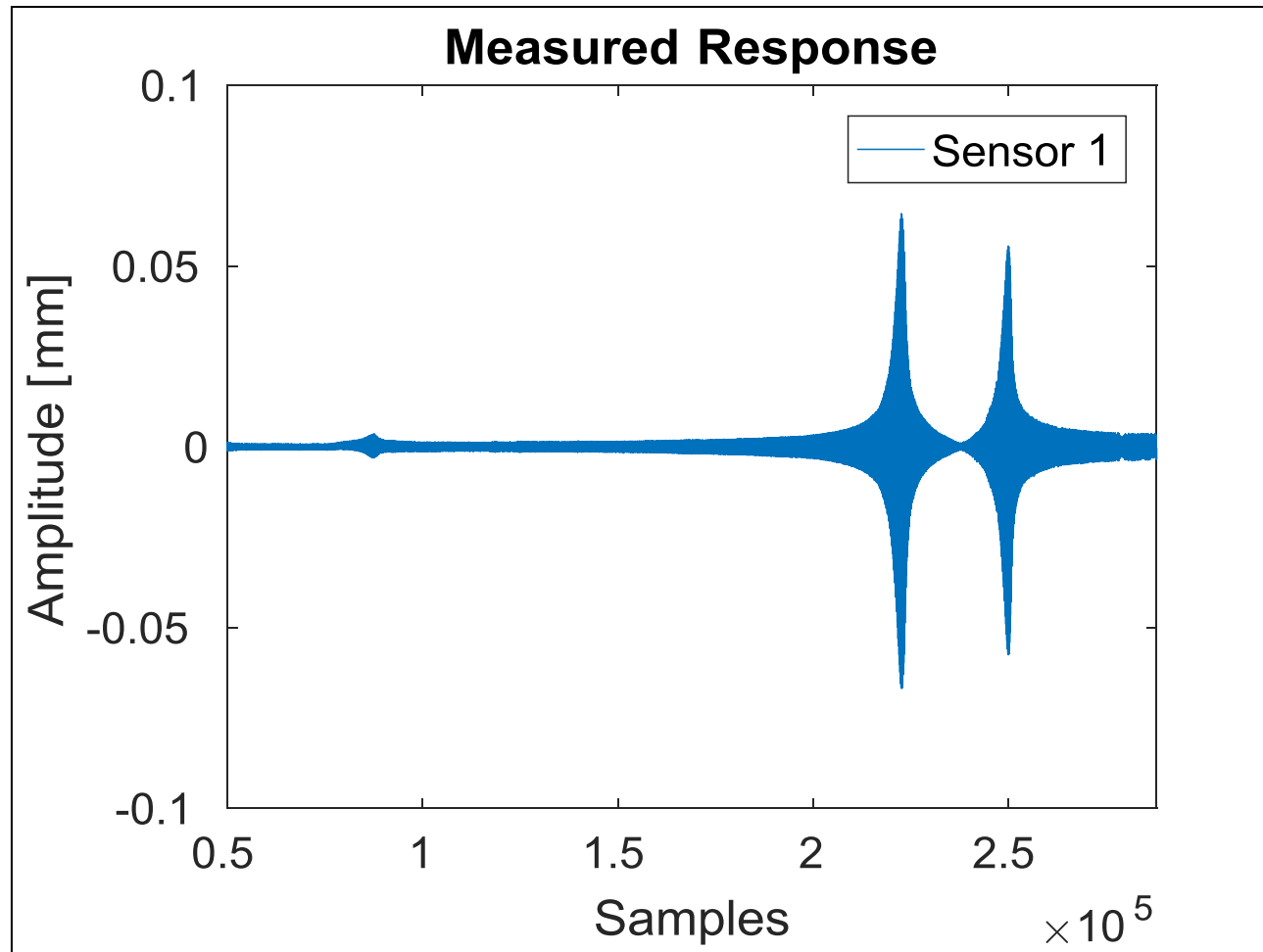
Rotor Modes



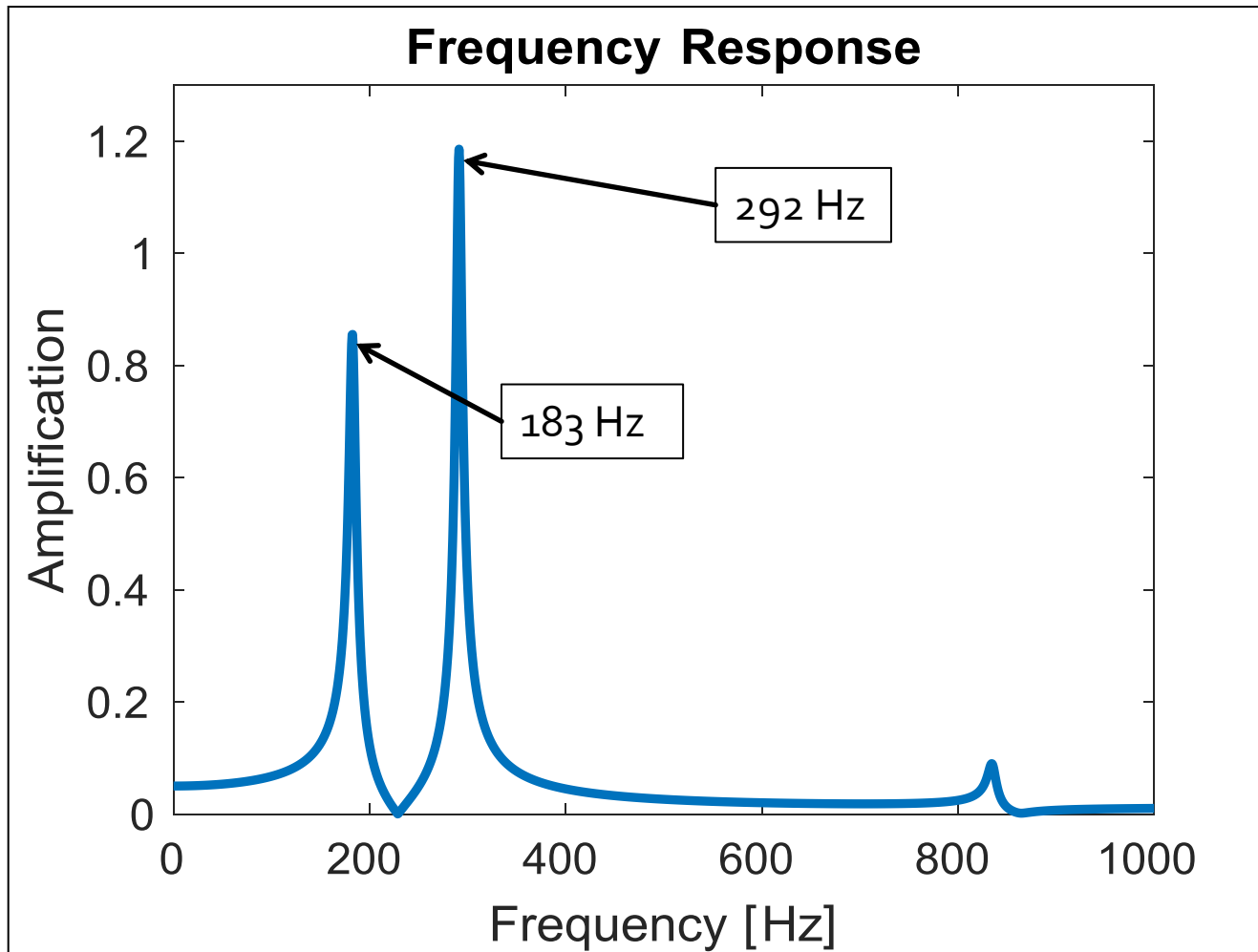
Voice Coil Actuators



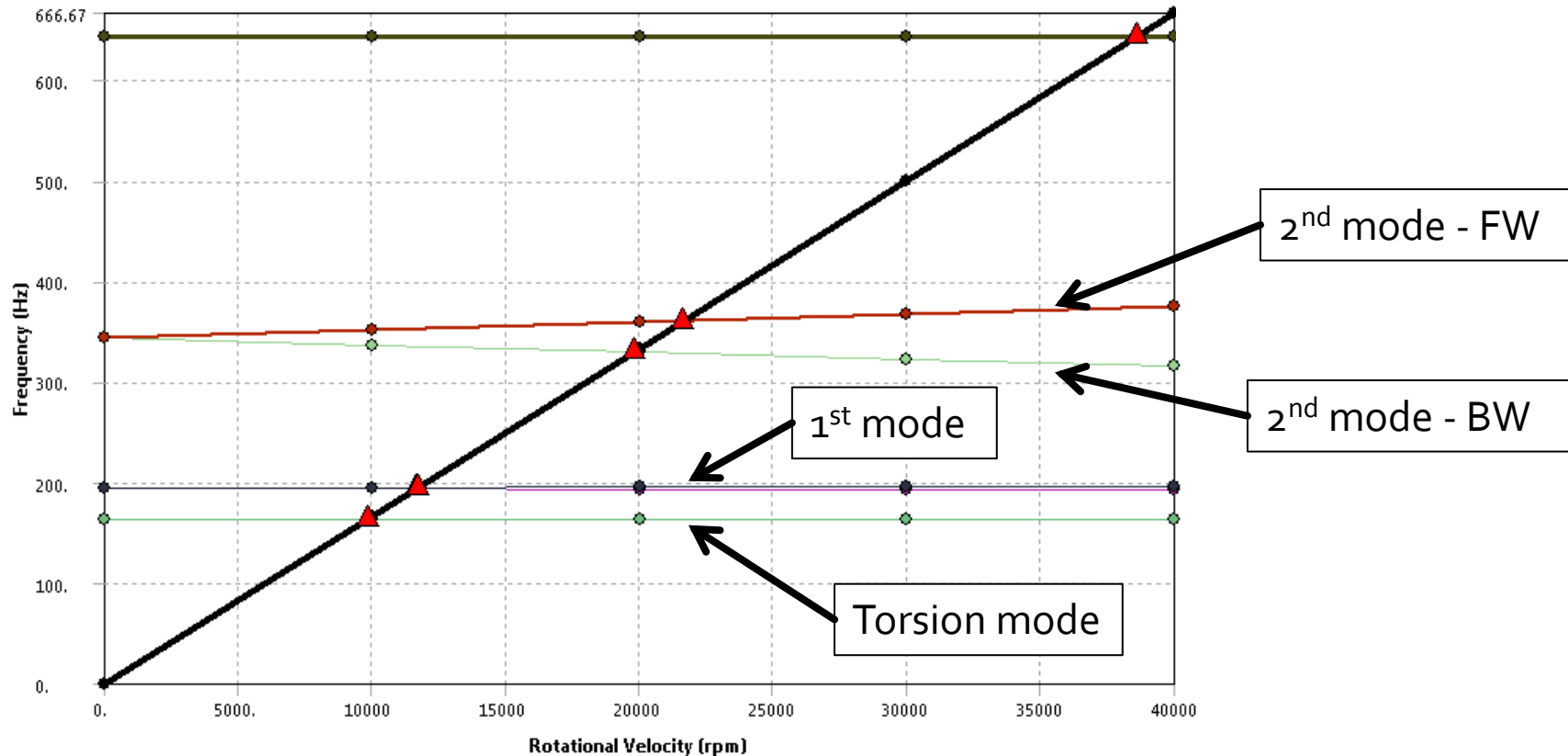
Non rotating excitation



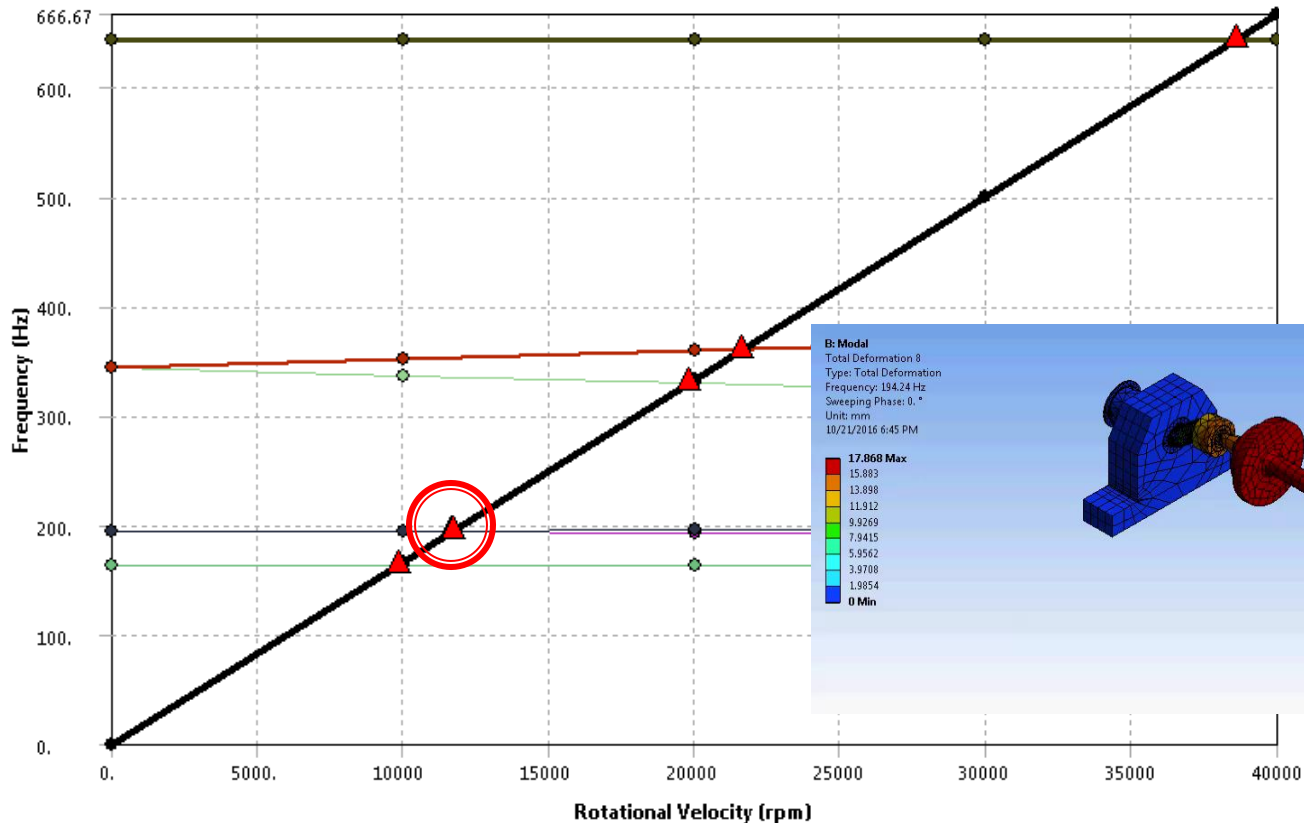
Non rotating excitation



■ Campbell diagram – Soft support



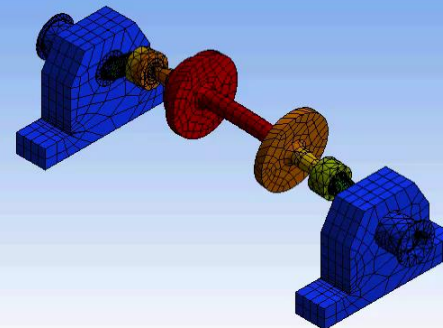
■ 1st Critical speed - Rigid body mode



11600 RPM

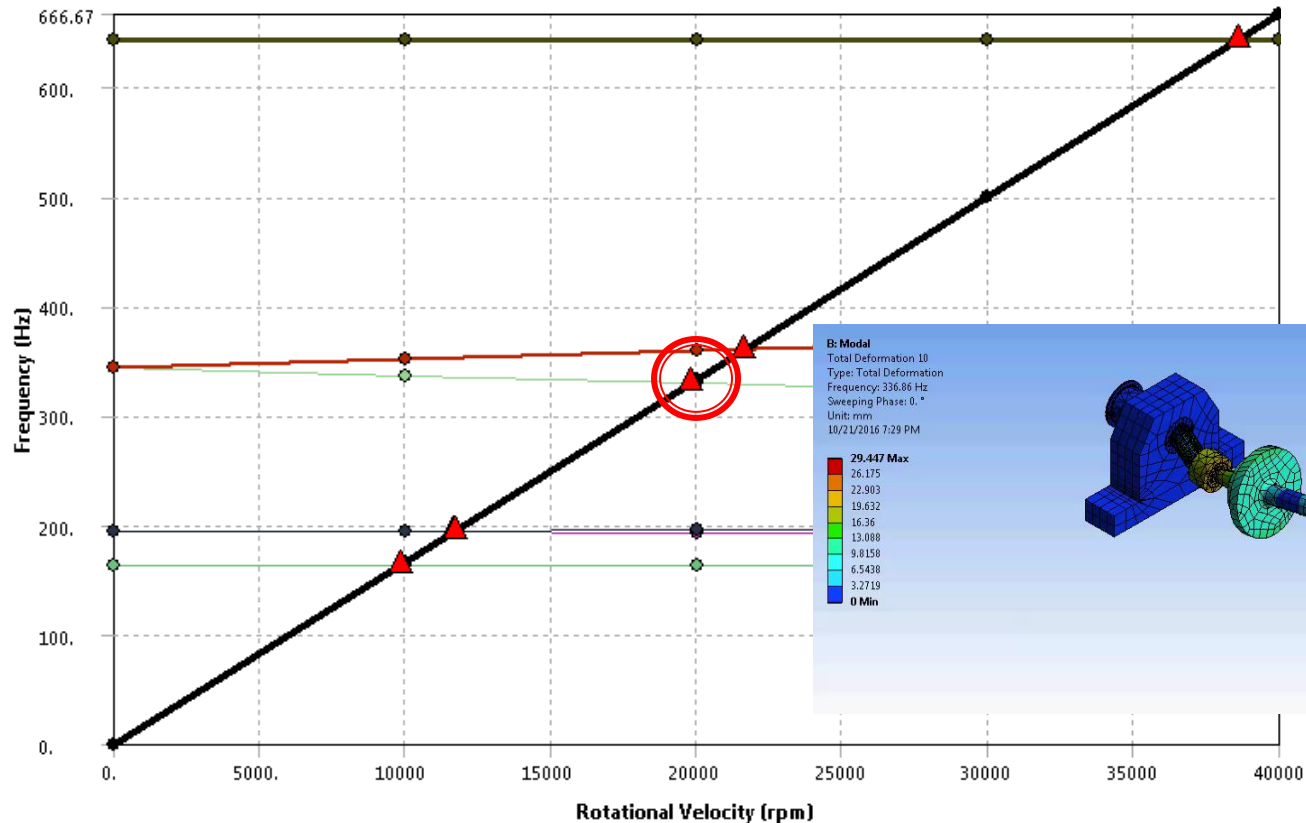
B: Modal
Total Deformation 0
Type: Total Deformation
Frequency: 19.424 Hz
Sweeping Phase: 0. °
Unit: mm
10/21/2016 6:45 PM

17.868 Max
15.883
13.898
11.912
9.9269
7.9415
5.9562
3.9708
1.9854
0 Min



ANSYS
R17.0
Academic

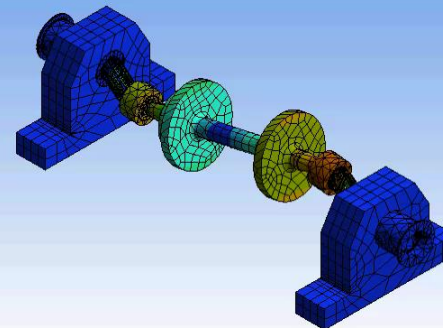
■ 2rd Critical speed - Rigid body mode BW



19800 RPM

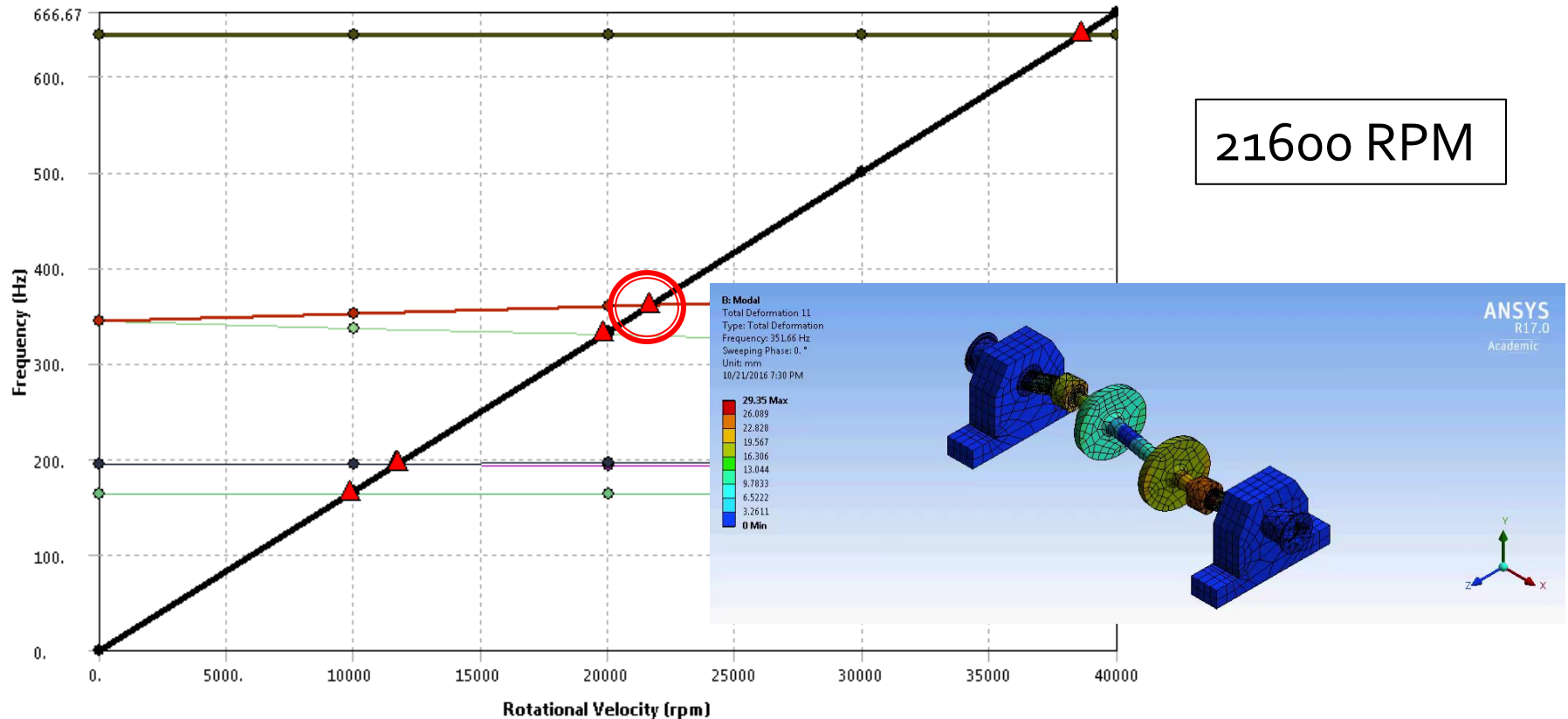
B: Modal
Total Deformation: 10
Type: Total Deformation
Frequency: 336.86 Hz
Sweeping Phase: 0. °
Unit: mm
10/21/2016 7:29 PM

29.447 Max
26.175
22.903
19.632
16.36
13.088
9.8158
6.5438
3.2719
0 Min

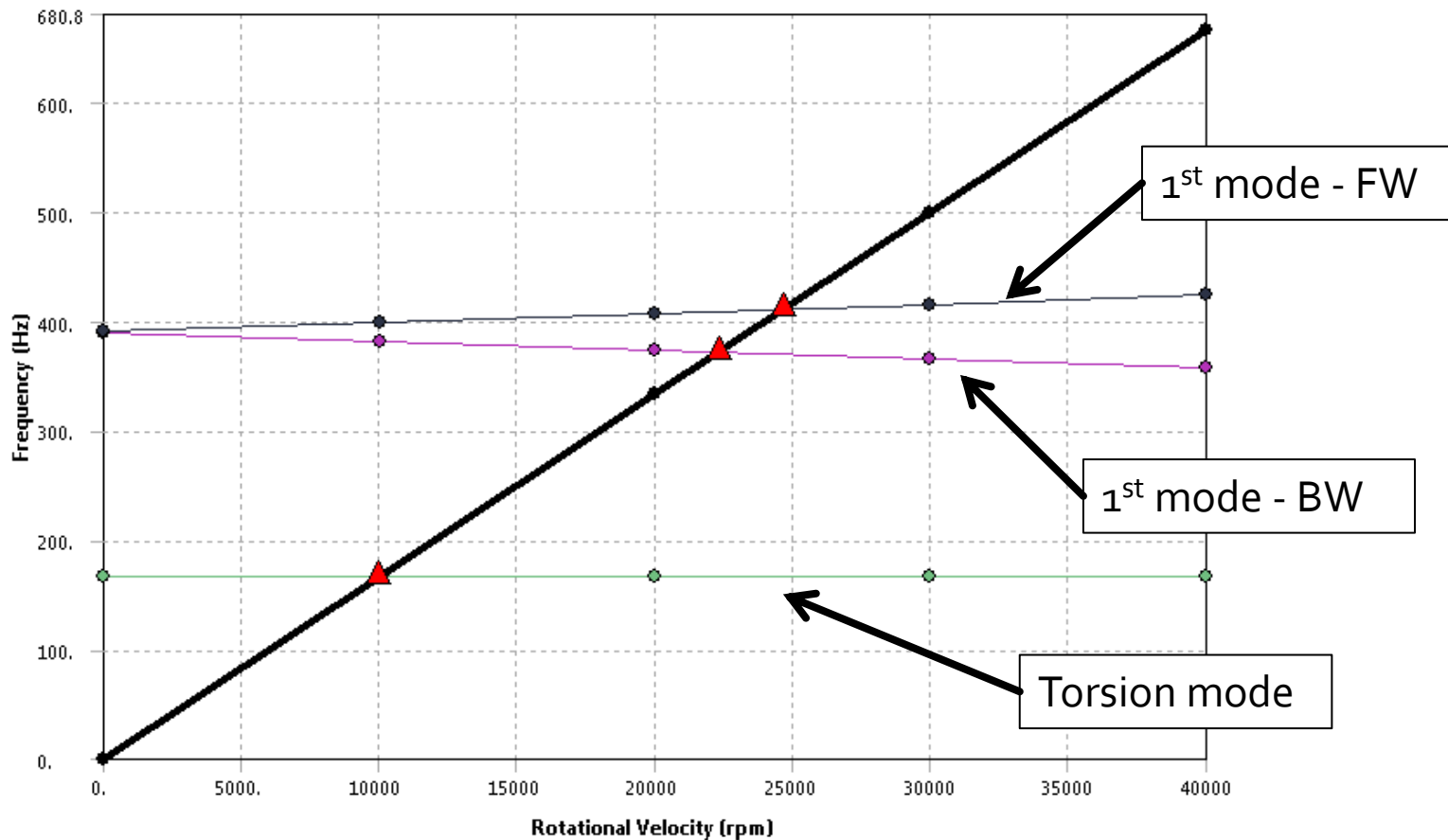


ANSYS
R17.0
Academic

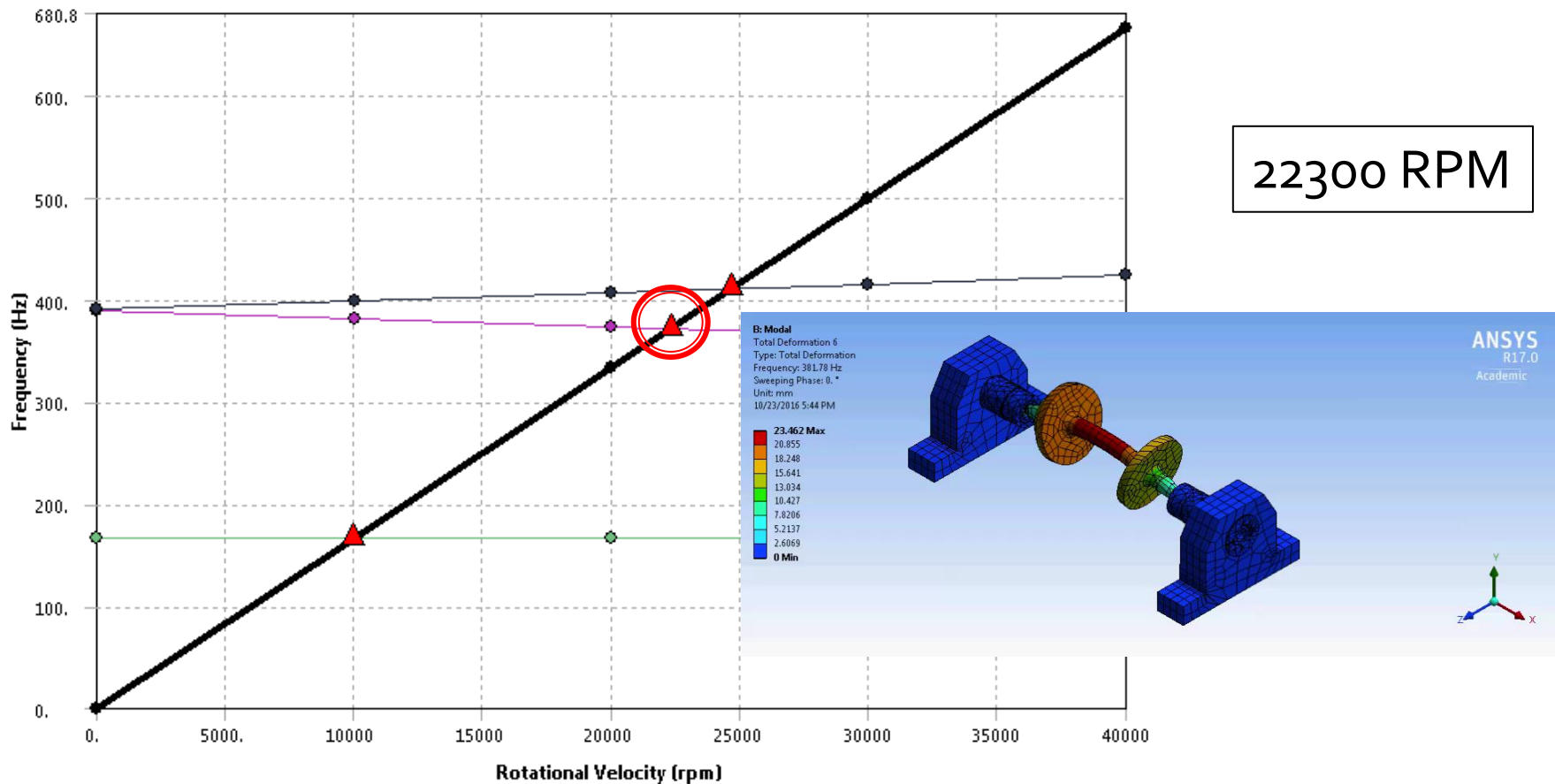
■ 2rd Critical speed - Rigid body mode FW



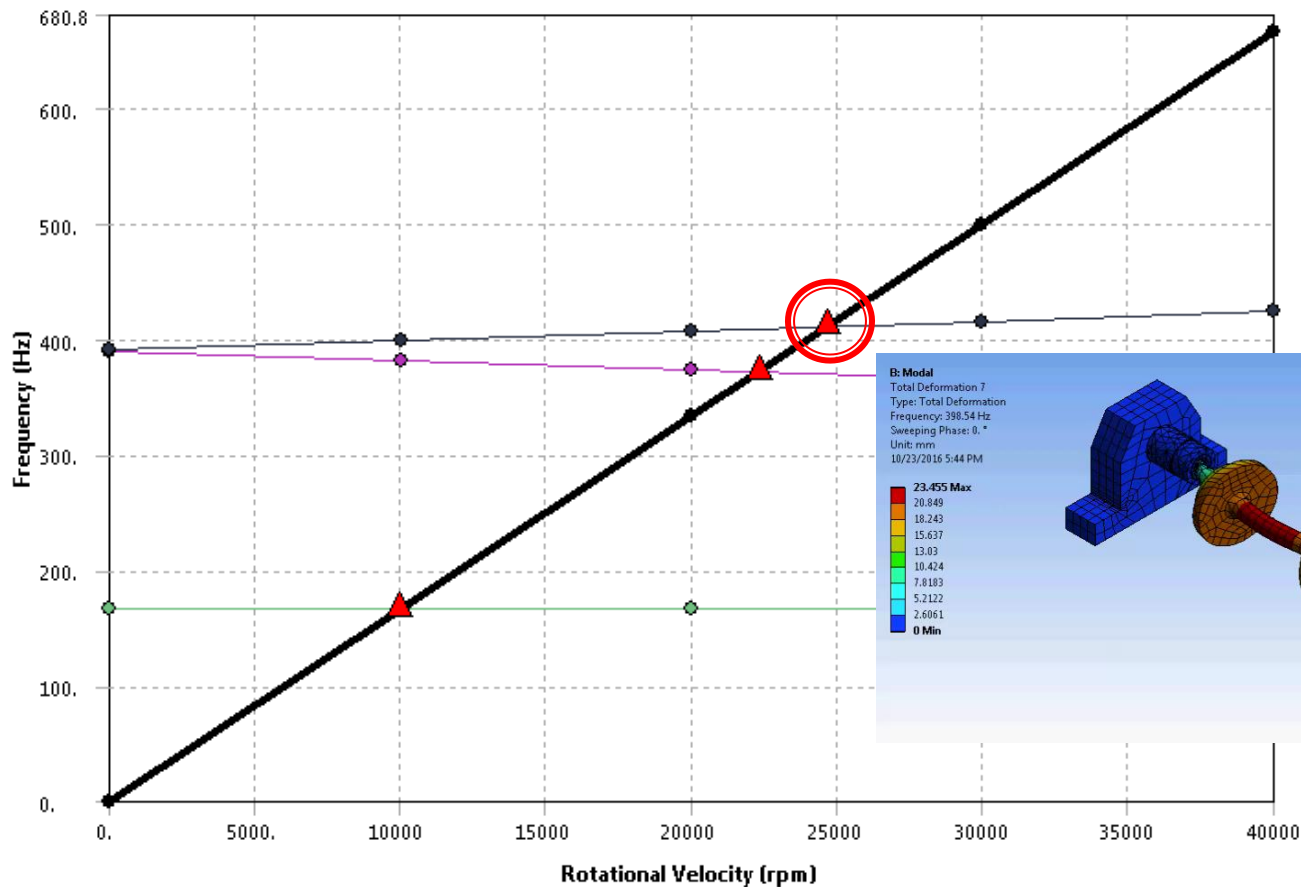
■ Campbell diagram – Stiff support



■ 1st Critical speed – Bending mode BW



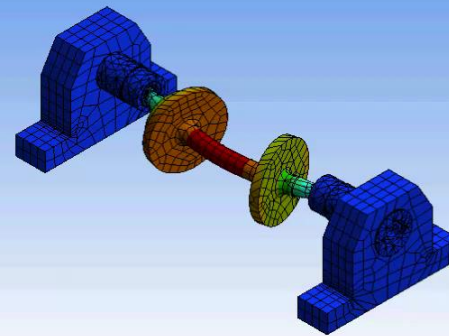
■ 1st Critical speed – Bending mode FW



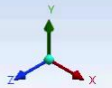
24700 RPM

B: Modal
Total Deformation 7
Type: Total Deformation
Frequency: 398.54 Hz
Sweeping Phase: 0. °
Unit: mm
10/23/2016 5:44 PM

23.455 Max
20.849
18.243
15.637
13.03
10.424
7.8183
5.2122
2.6061
0 Min



ANSYS
R17.0
Academic

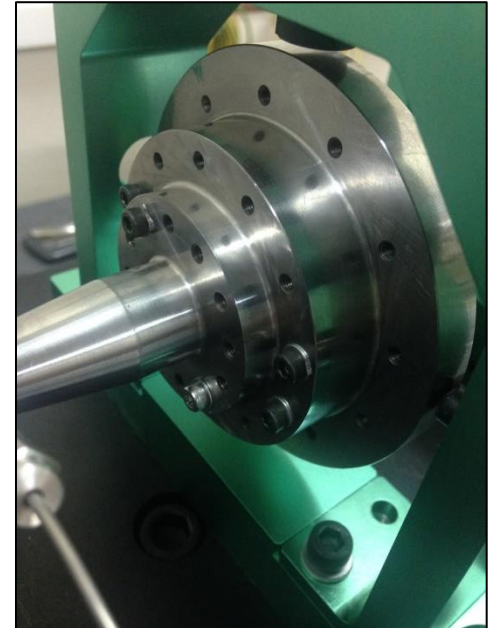


Balancing



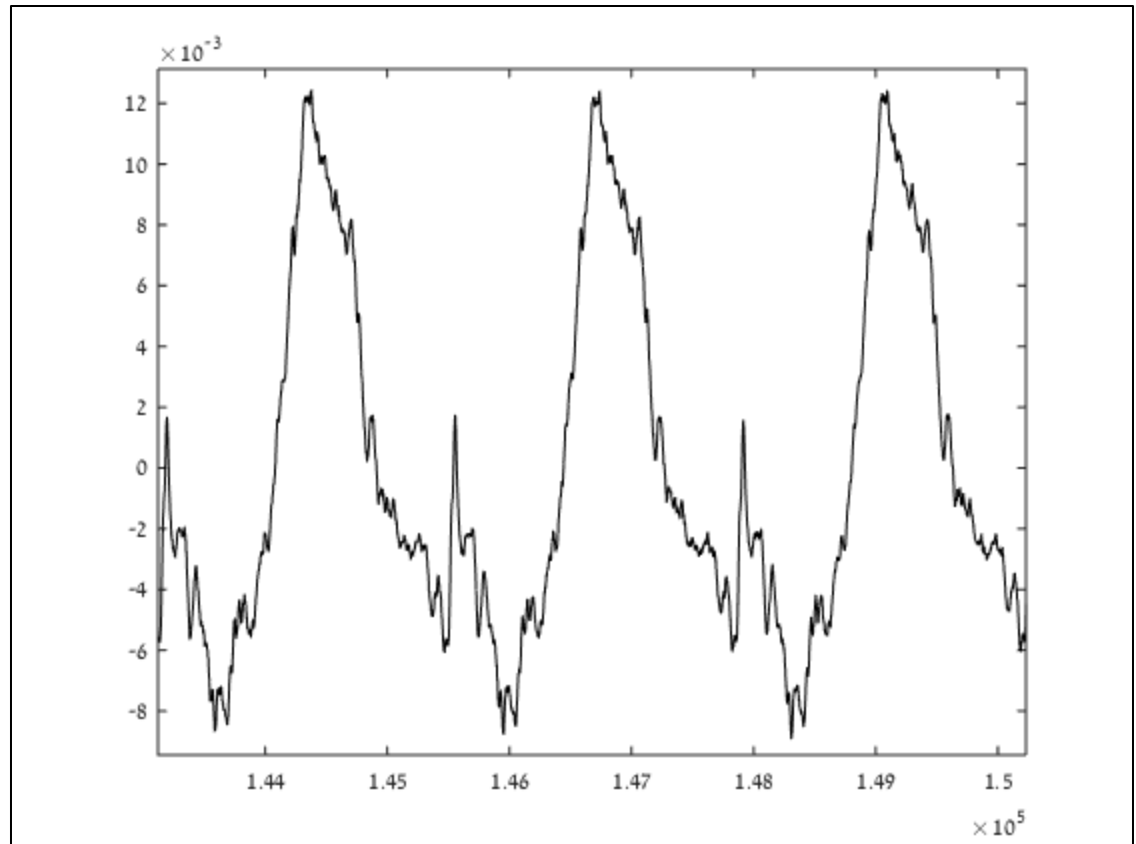
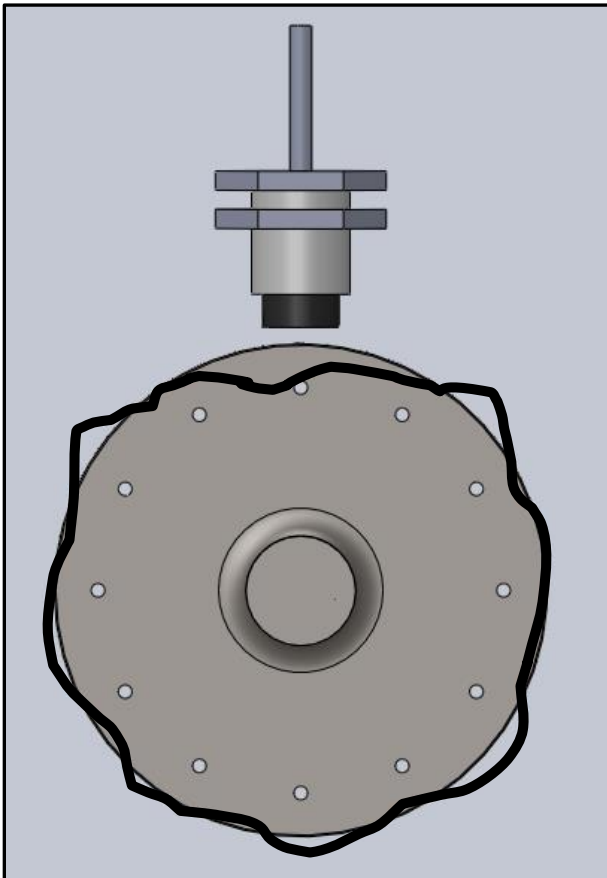
■ Influence Coefficients method

$$\boxed{\text{Dynamic Response}} = \boxed{\text{Unbalance}} \times \boxed{\text{Influence Coefficients}}$$



$$\boxed{\begin{array}{l} \text{Dynamic Response} + \\ \Delta \text{ Dynamic Response} \end{array}} = \boxed{\begin{array}{l} \text{Unbalance} + \\ \Delta \text{ Unbalance} \end{array}} \times \boxed{\text{Influence Coefficients}}$$

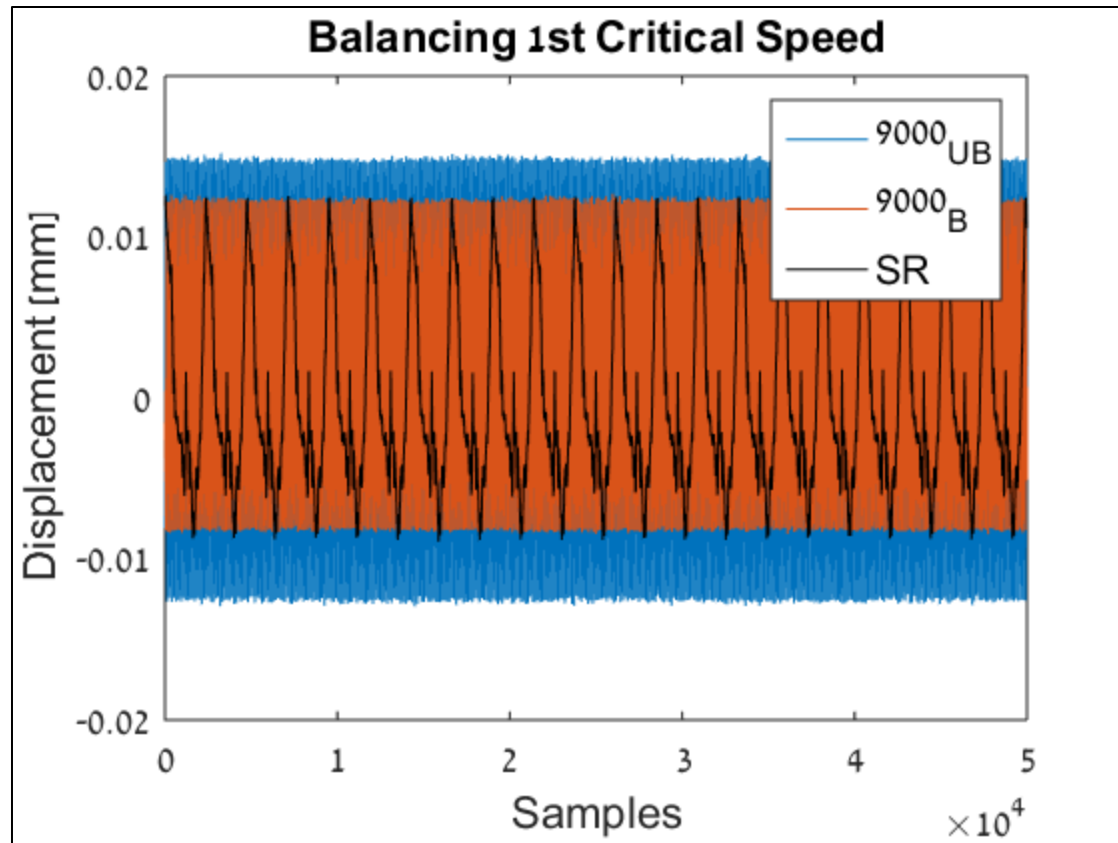
- Static Runout at 500 RPM



Balancing



- Balancing 1st critical speed at 9 kRPM

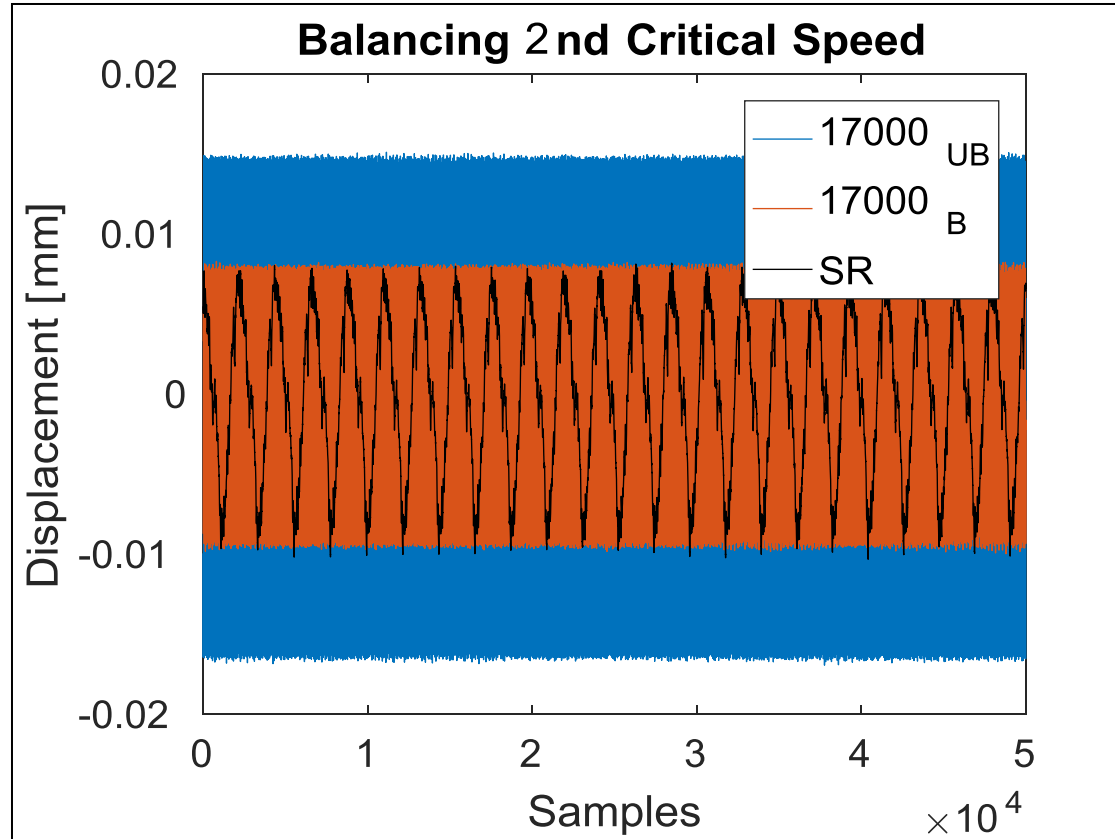


Unbalanced
Balanced
Static runout

Balancing



- Balancing 2nd critical speed at 17 kRPM

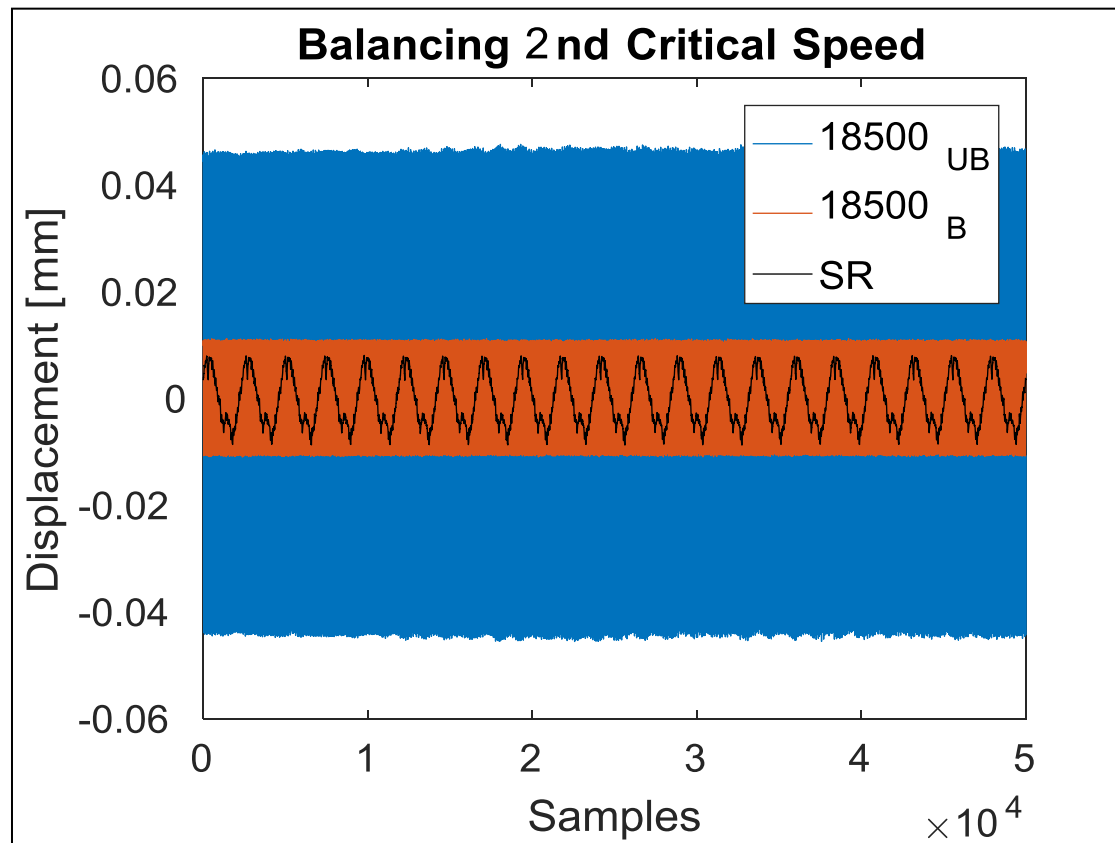


Unbalanced
Balanced
Static runout

Balancing

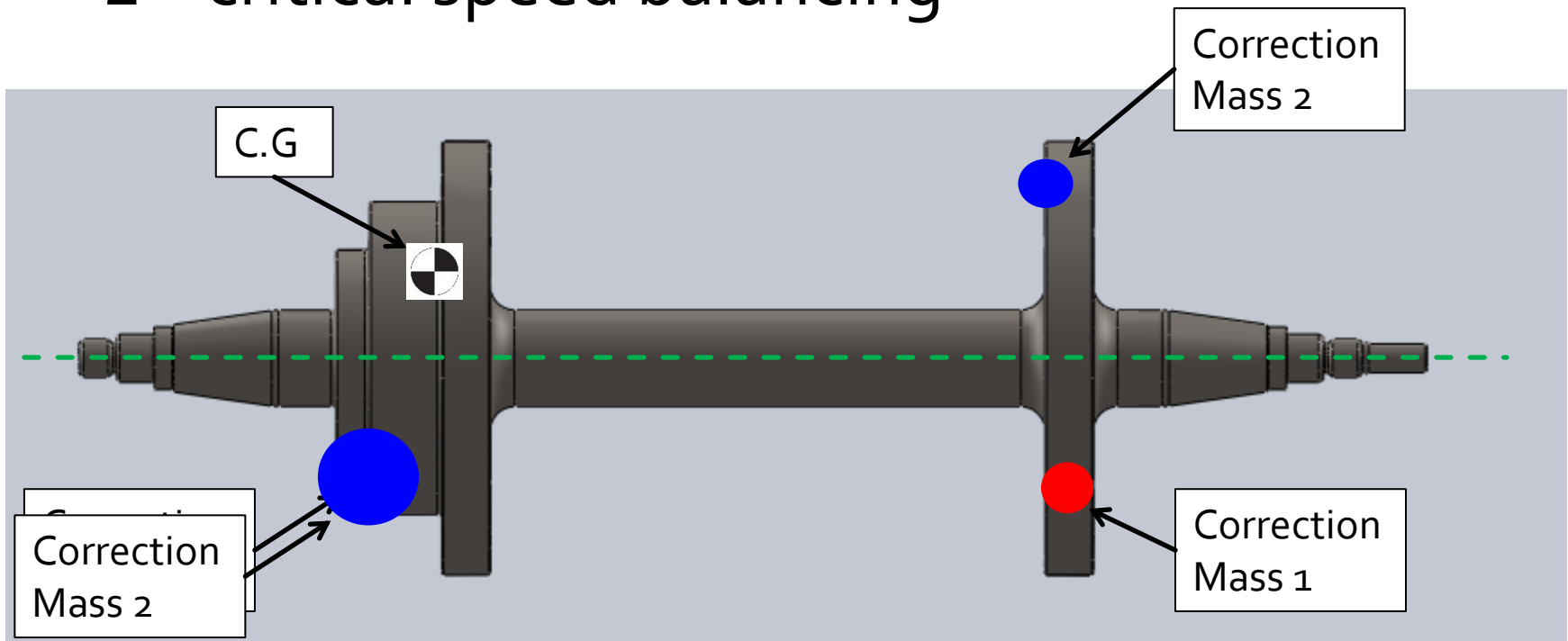


- Balancing 2nd critical speed at 18.5 kRPM

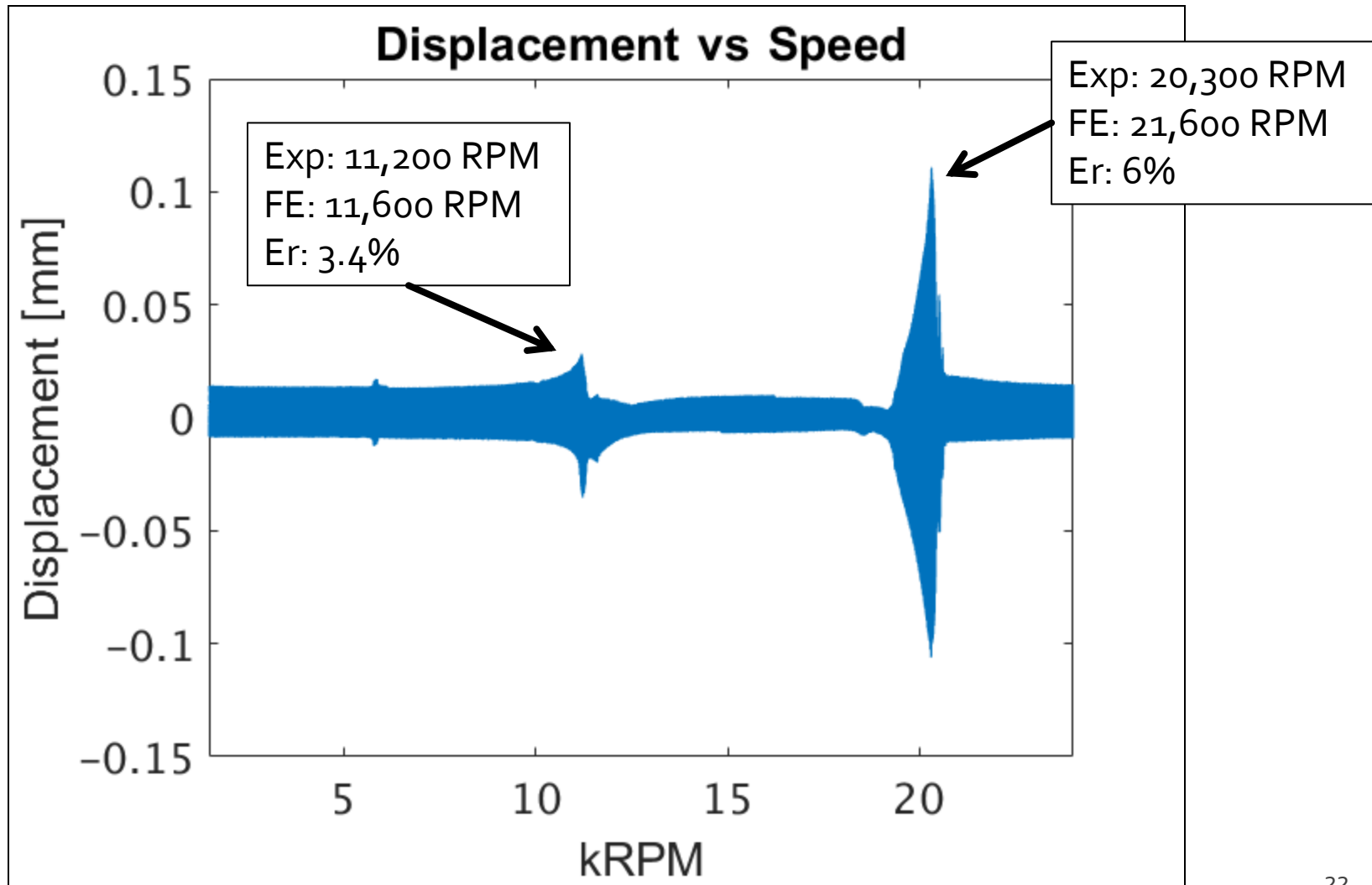


Unbalanced
Balanced
Static runout

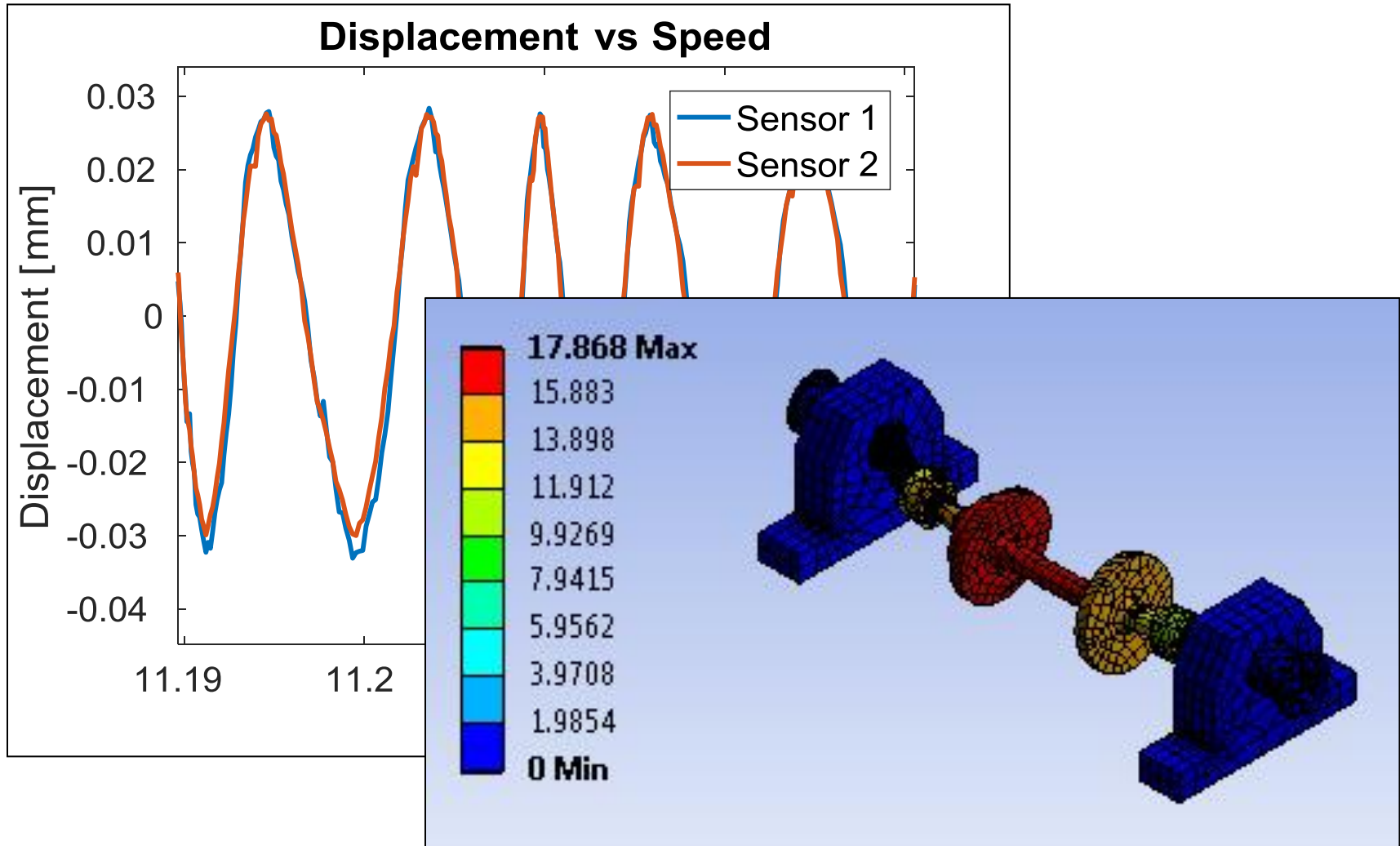
■ 2nd critical speed balancing



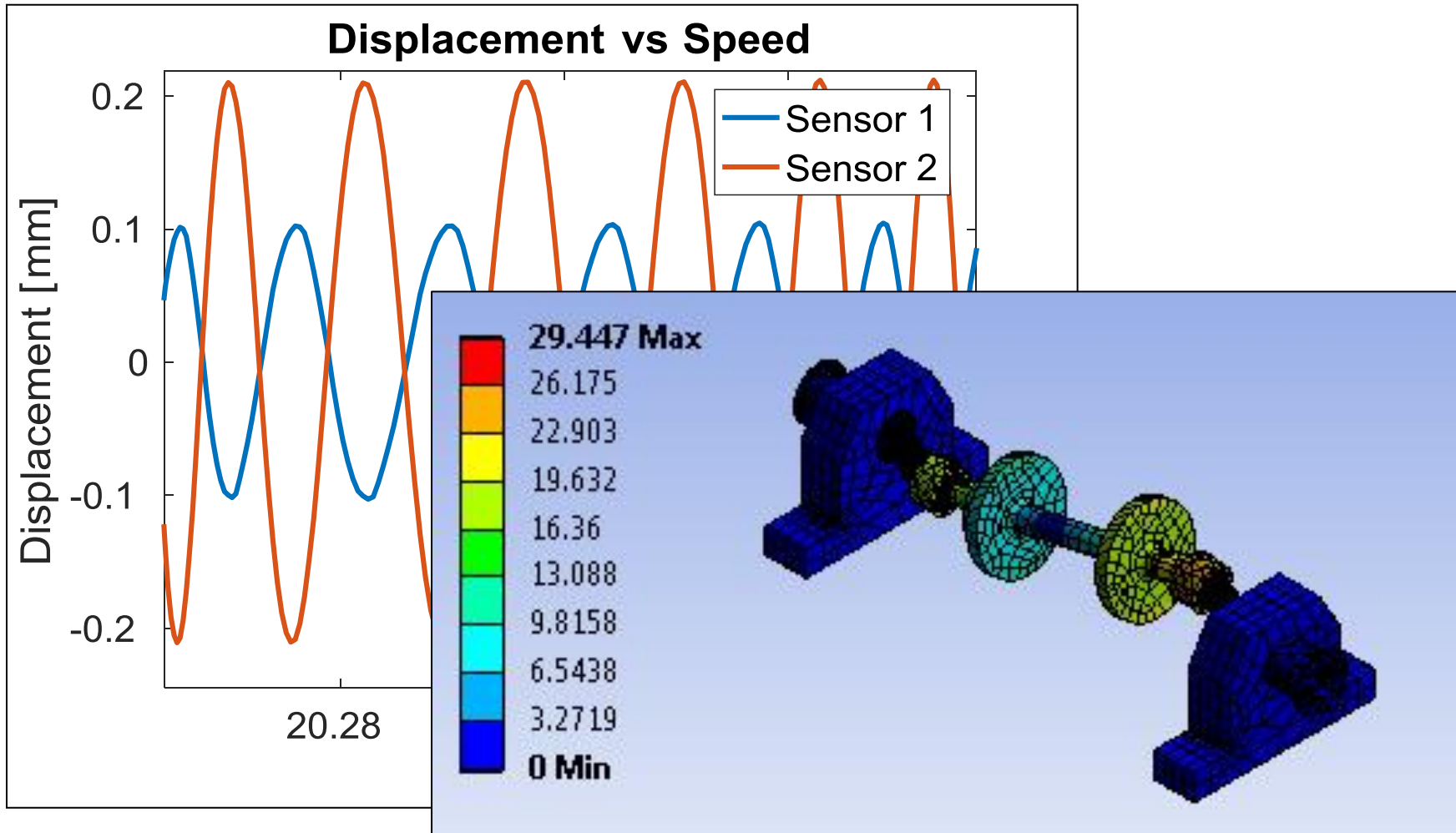
Transient measurements



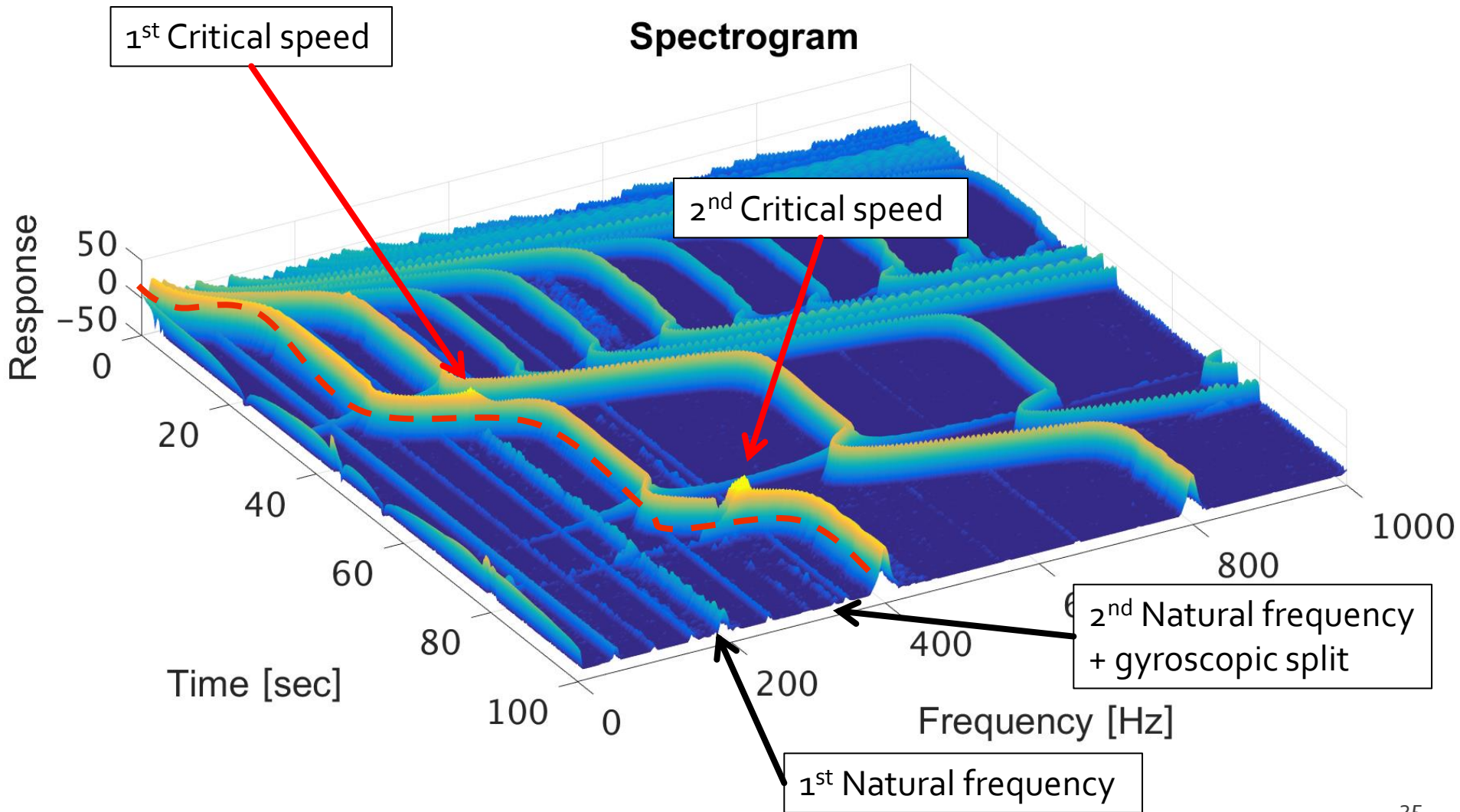
Transient measurements



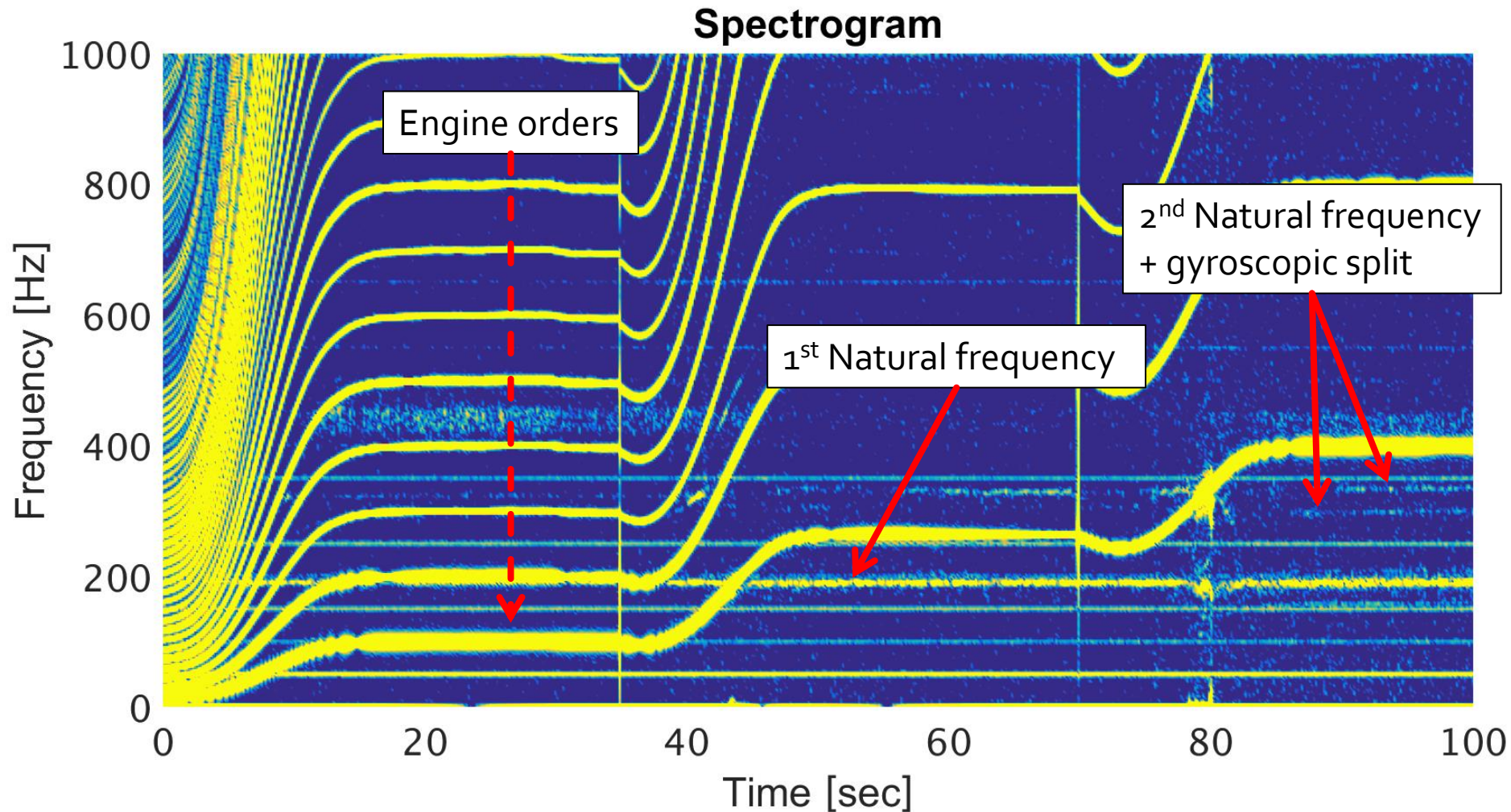
Transient measurements



Transient measurements



Transient measurements



- Full rotor-dynamics simulation with laboratory test rig
- FE analysis of modes, critical speeds and gyroscopic effect
- Balancing according to Influence Coefficient method
- Signal processing and comparison to simulations

Future plans



- Transient measurements with stiff supports.
- Implementing Voice Coil actuators to simulate squeeze-film dampers.
- Reconcile finite element models with experiments
- Investigating the method of balancing fast rotors while rotating at low speeds

Questions

