

Experimental Framework for Closed-loop Control of Micro-jet Engines

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Educational Project:

“Closed-loop control of micro jet engines”

The project long-term research goal:
to study and test different engine control strategies of the thermodynamic systems.

The project framework objectives:
to develop the experimental testbed
providing **rapid implementing** of the real-time control algorithms

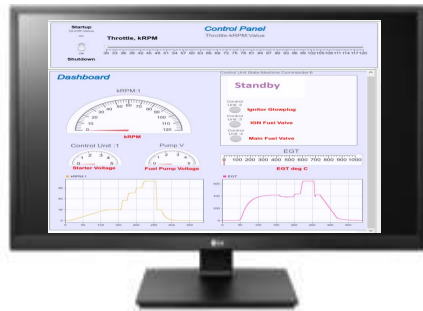
Control Performance Requirements:

- Steady-state error
- Settling time
- Maximum overshoot
- Maximum undershoot
- Minimum Stall Margin

Protection against:

- Maximum Rotational Speed
- Maximum Combustor Outlet Temperature
- Compressor Surge
- Overheating of the Turbine blades
- Rich/ Weak Flameout,

Jet Engine Closed-loop Control

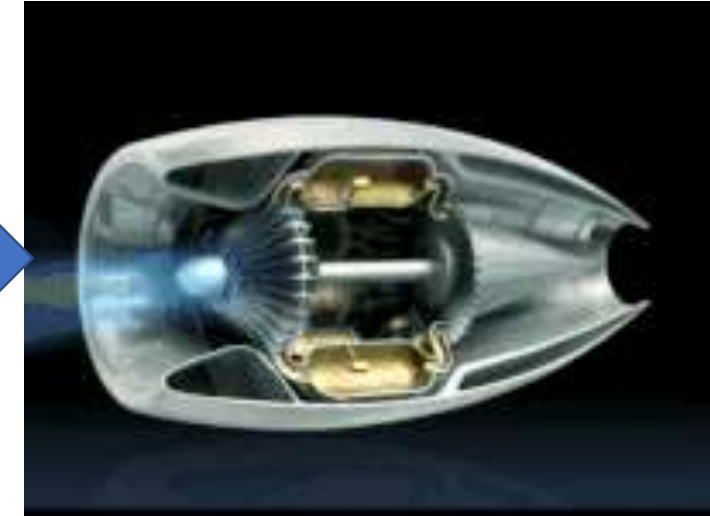


Control Panel
Operator Commands



Electronic Control Unit (ECU)

The company-supplied
AMT Netherlands
built-in microprocessor



Jet engine

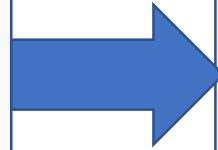
RPM
EGT

Feedback

Electronic Control Unit (ECU)



The company-supplied AMT Netherlands ECU built-in microprocessor, which cannot be changed or reprogrammed.



dSPACE Hardware/ Software



MicroLabBox

Matlab/Simulink/dSpace: a powerful and flexible computing environment for control algorithm design, modeling and analysis

For the project purposes, the original ECU should be replaced with a special designed control unit based on intuitive and flexible software/hardware tools.

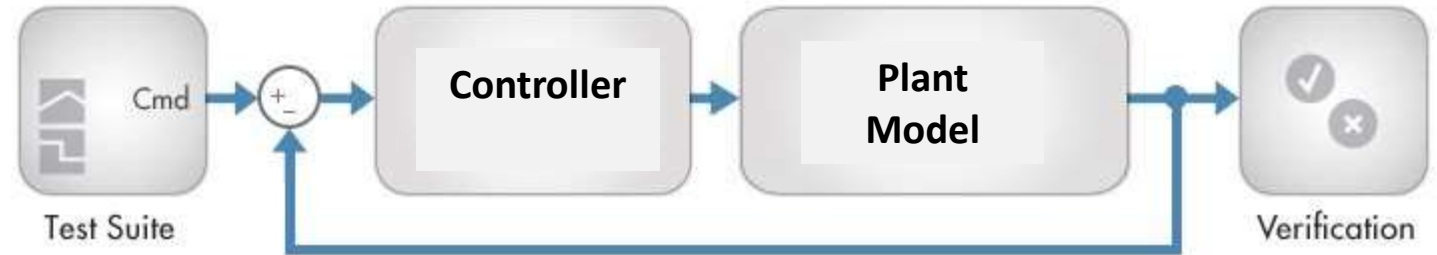
From the Simulation to the Implementation

Software in the loop simulation.

Non Real-Time Closed loop System



Matlab
Simulink



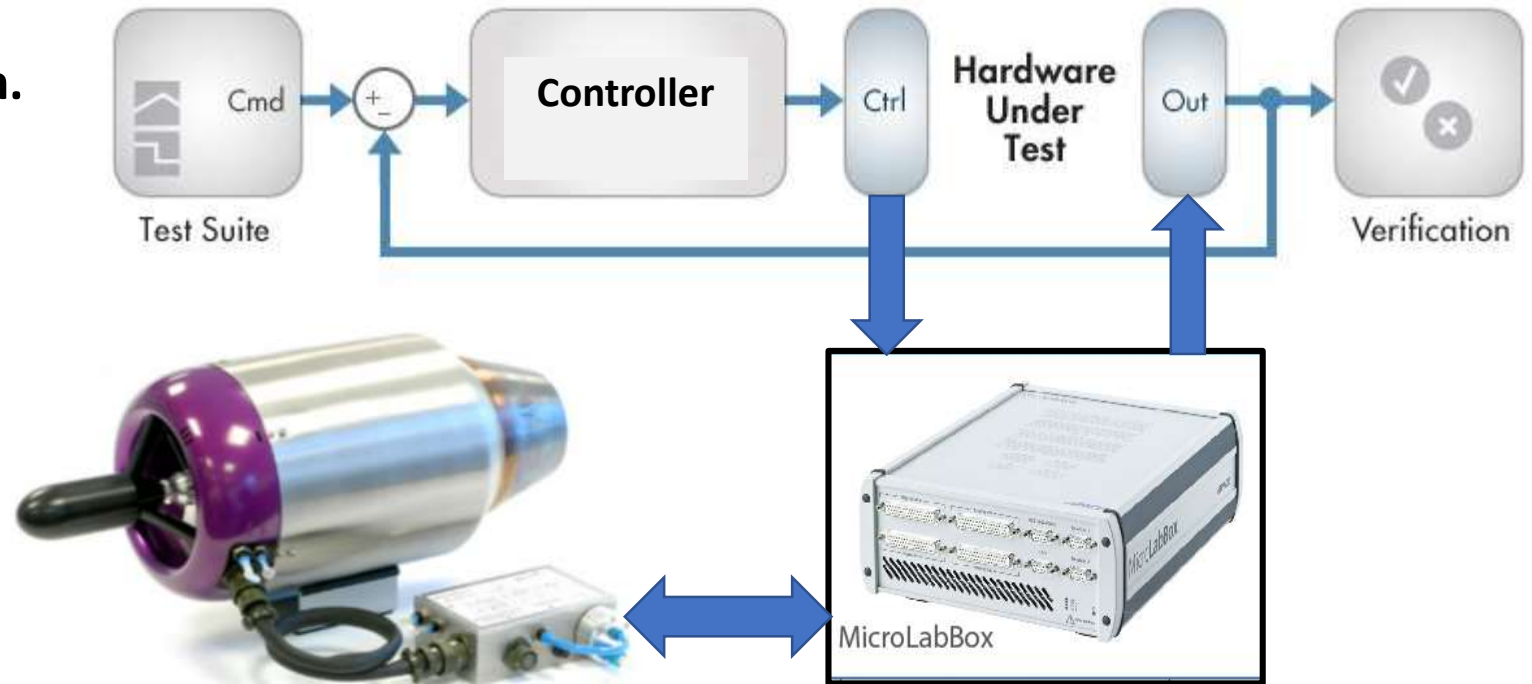
Hardware in the loop simulation.

Real-Time Closed loop System

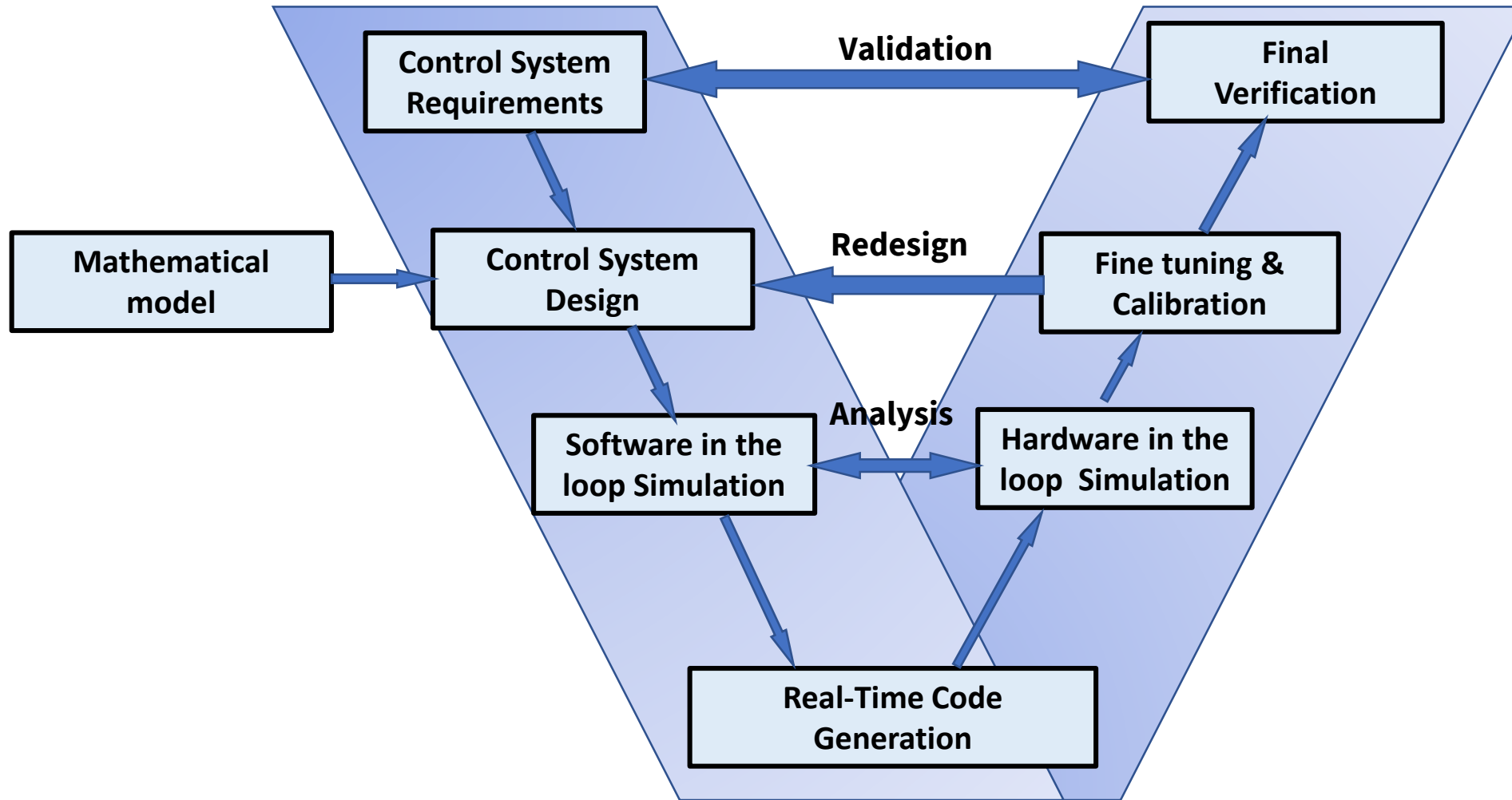


Matlab
Simulink

dSPACE

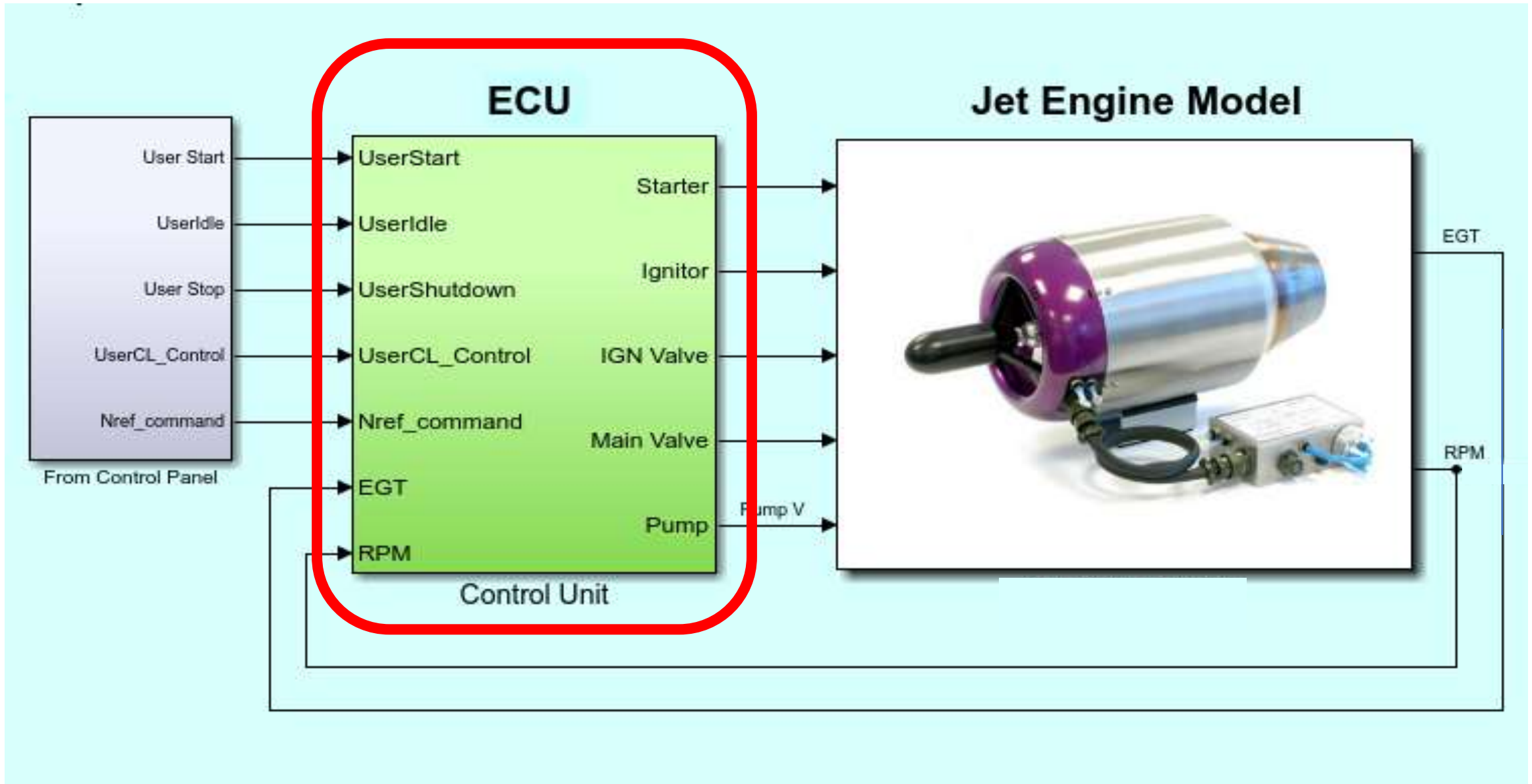


Rapid Control Prototyping Concept

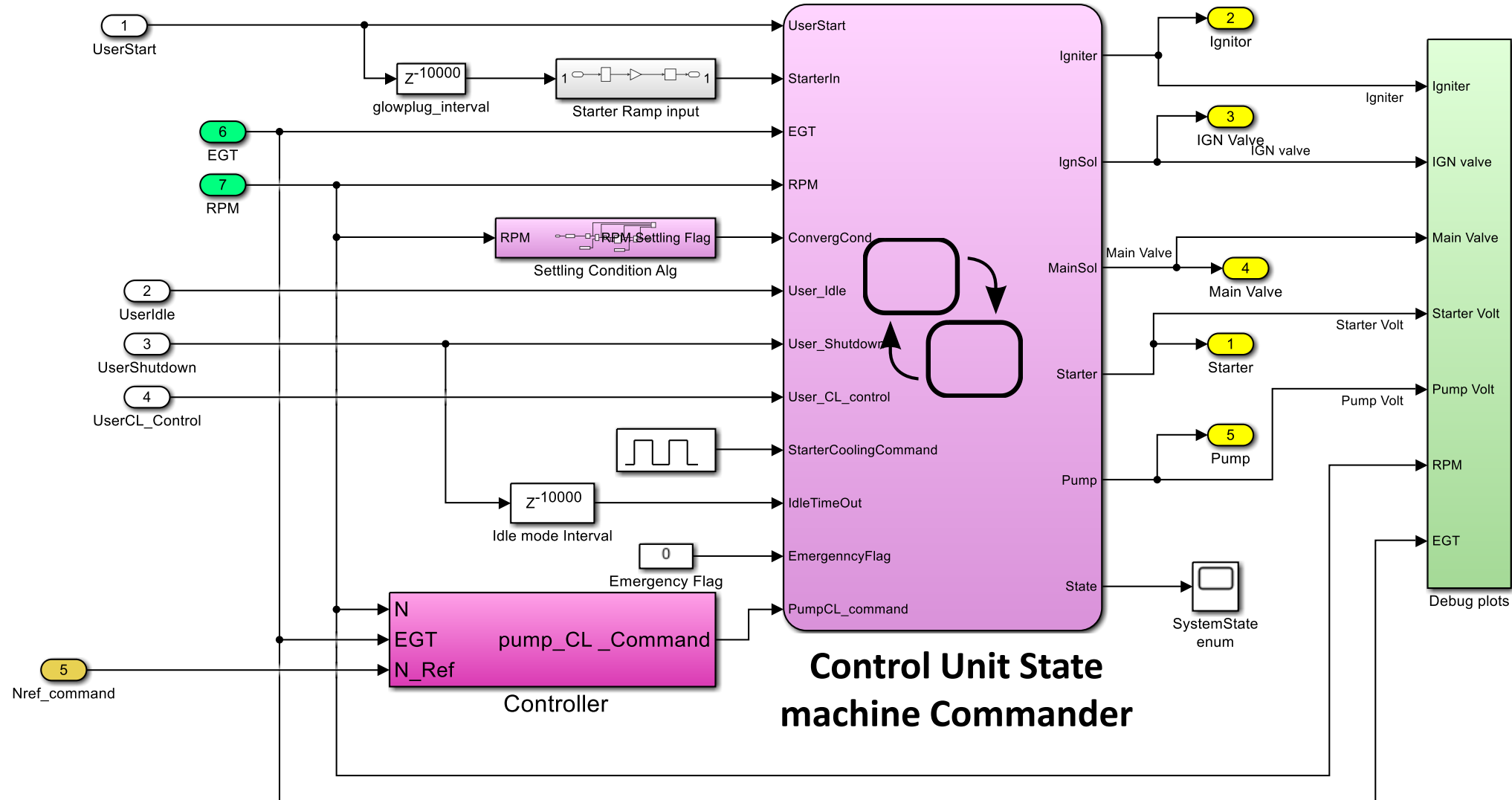


Typical V-cycle for the modern design of control system

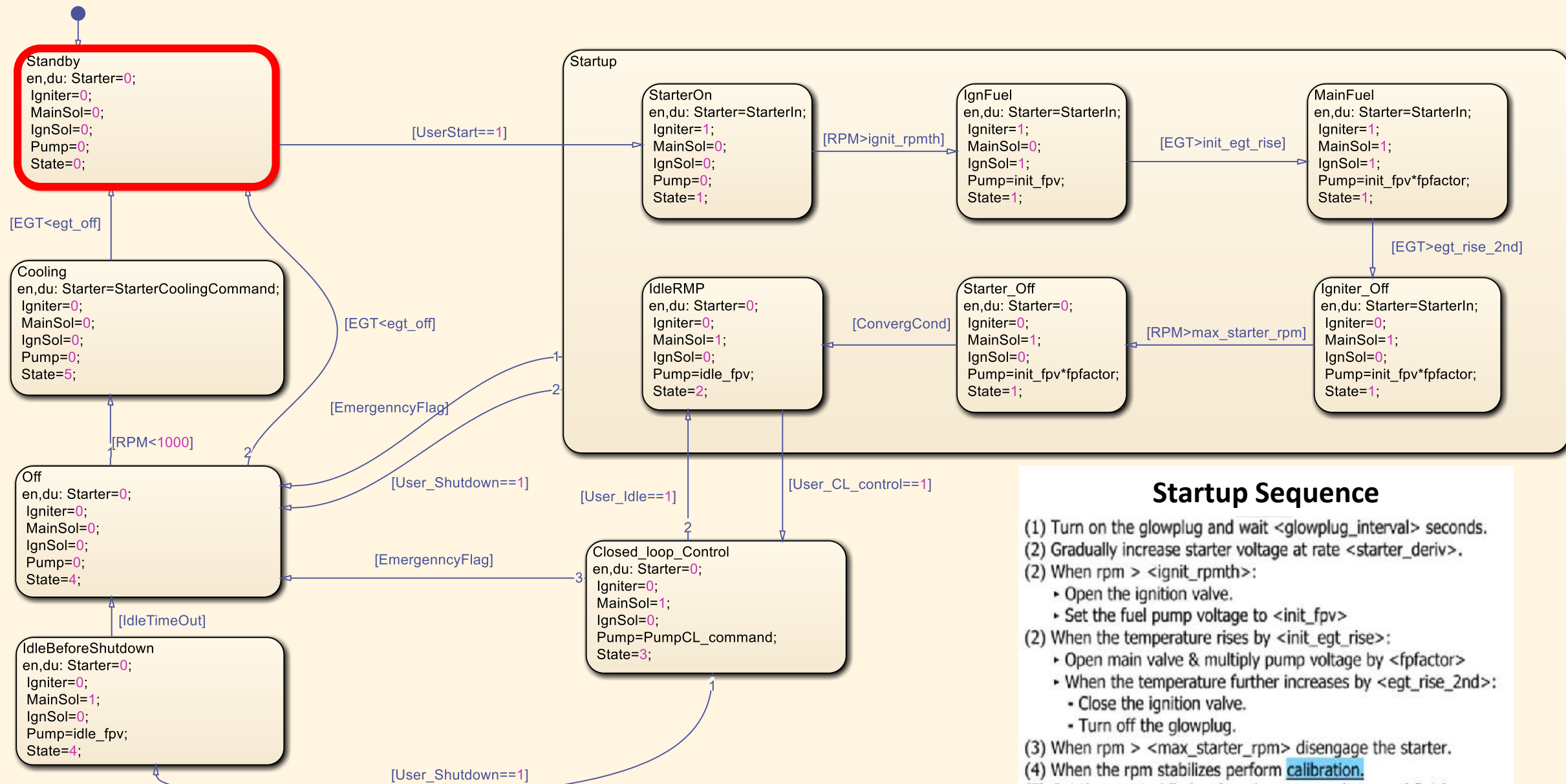
Turbo Jet Engine non-real time Simulation



Control Unit



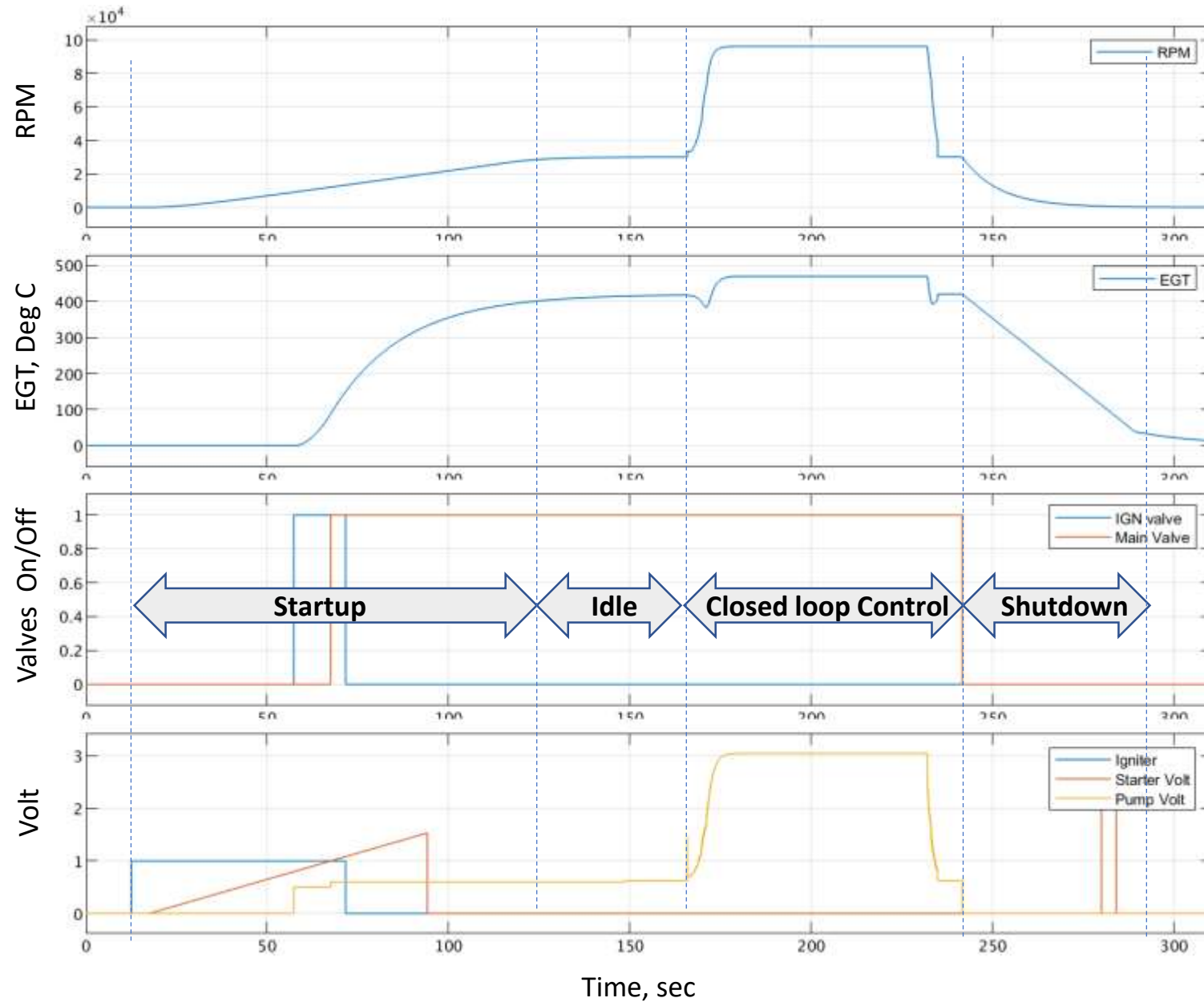
Control Unit State-Machine Commander



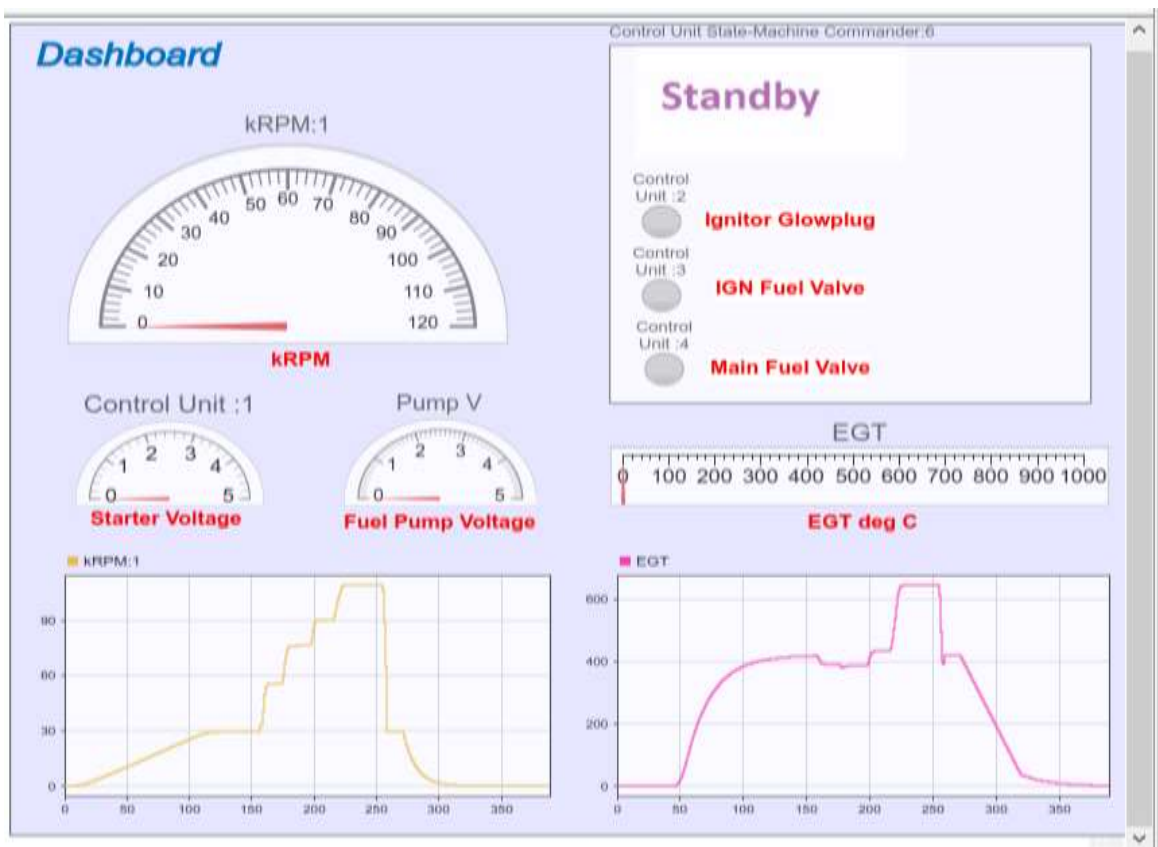
Startup Sequence

- (1) Turn on the glowplug and wait `<glowplug_interval>` seconds.
- (2) Gradually increase starter voltage at rate `<starter_deriv>`.
- (2) When `rpm > <ignit_rpmth>`:
 - Open the ignition valve.
 - Set the fuel pump voltage to `<init_fpv>`
- (2) When the temperature rises by `<init egt_rise>`:
 - Open main valve & multiply pump voltage by `<fpfactor>`
 - When the temperature further increases by `<egt_rise_2nd>`:
 - Close the ignition valve.
 - Turn off the glowplug.
- (3) When `rpm > <max_starter_rpm>` disengage the starter.
- (4) When the rpm stabilizes perform calibration.
- (5) Get the rpm to idle by changing pump voltage and finish.

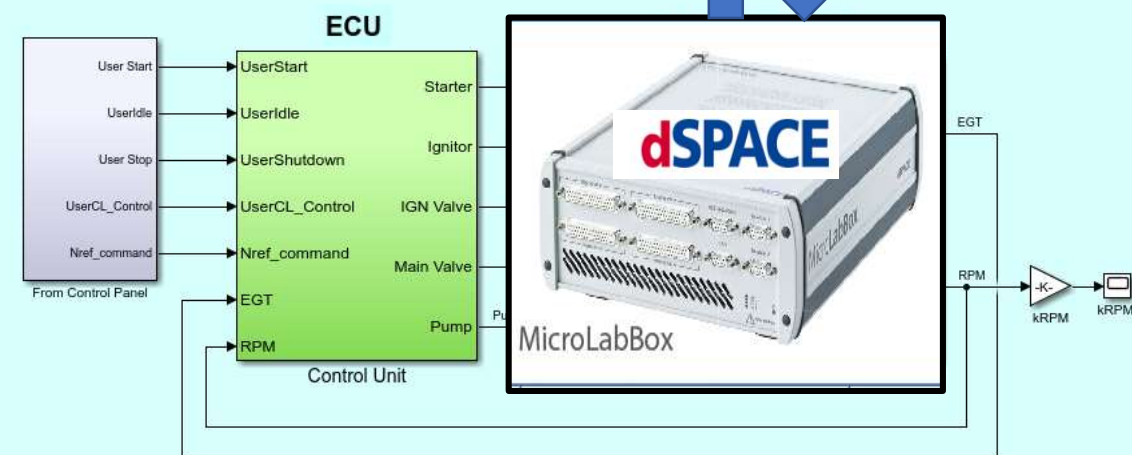
Preliminary Simulation Results



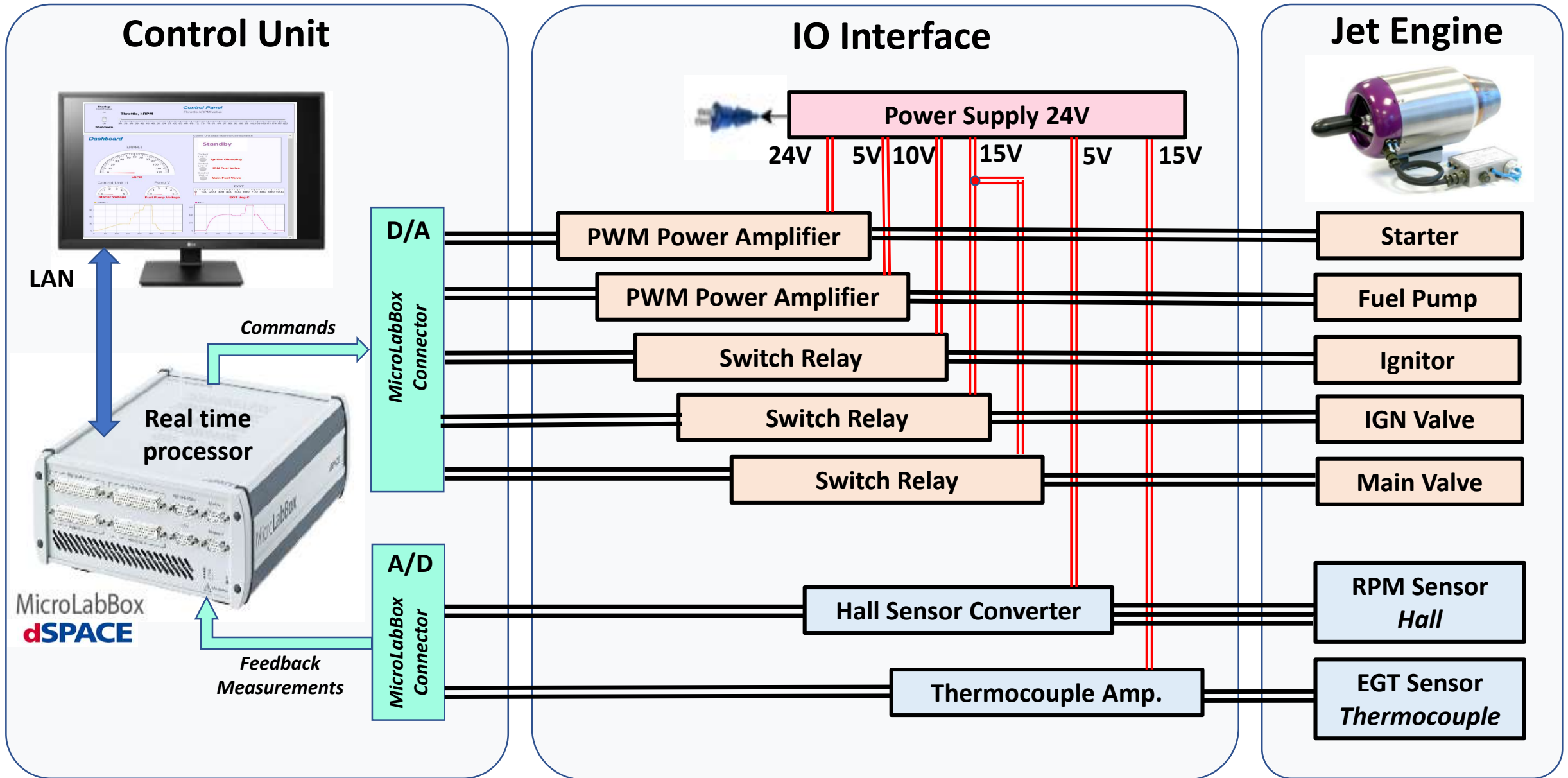
Turbo Jet Engine End-to-end HIL Simulation



Simulink + dSpace



Implementation: Wiring Connections Diagram



The Testbed



I/O interface



Olympus micro-turbine Jet Engine

Thank you
for your attention

